### Exams

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## Randomness for testing

Randomness used to test a property (specific state, Bell violation,...)

- Many systems  $Y_1 \dots Y_n$
- Want: testing random subset enough to guarantee global property

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Another property we would like to test:

Has student 
$$B$$
 learned the data  $X_1 \dots X_n$ ?

Want: testing random subset enough to guarantee global learning

## Probabilistic model

### Systems:

- Data:  $X_1, \ldots, X_n \in \{0, 1\}^n$
- Student memory: *B* (could be classical or quantum)

Modeled by a joint distribution  $P_{X_1...X_nB}$ 

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#### Test:

- Exam:  $\vec{i} = (\vec{i}_1, ..., \vec{i}_k)$  with  $\vec{i}_p \in \{1, ..., n\}$
- Given *B* and  $\vec{i}$ , answer  $A^{\vec{i}} = A^{\vec{i}}(B, \vec{i}) \in \{0, 1\}^k$
- Grade given by  $G_k = \sum_{p=1}^k \mathbf{1}_{X_{\vec{i}_p} = A_p^{\vec{i}}} = k d_H(X_{\vec{i}}, A^{\vec{i}})$

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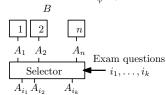
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Think of the student as the adversary

## Exam strategies

$$\begin{array}{ll} \textbf{Notation: Data:} \ X_1 \dots X_n \in \{0,1\}^n & \text{Exam: } \vec{i} = (\vec{i}_1,\dots,\vec{i}_k) \ \text{with } \vec{i}_p \in \{1,\dots,n\} \\ \text{Student memory } B & \text{Answer } A^{\vec{i}} = A^{\vec{i}}(B,\vec{i}) \in \{0,1\}^k & \text{Grade } \mathsf{G}_k(A^{\vec{i}}) = \sum_{p=1}^k \mathbf{1}_{X_{\vec{i}_p} = A_{\vec{i}_p}^{\vec{i}}} \end{array}$$

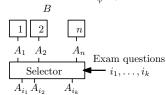
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Special kind of strategy:
Simple strategies

Selector
$$A_{i_1} A_{i_2} A_{i_k}$$
Exam questions
$$B$$
General strategy
$$A_{i_1} A_{i_2} A_{i_k}$$
Exam questions
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In general strategies, answer to question *i* depends on context

Notation: Data:  $X_1, \ldots, X_n$ 

Exam: 
$$\vec{i} = (\vec{i}_1, \dots, \vec{i}_k)$$
 with  $\vec{i}_p \in \{1, \dots, n\}$ 

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$$A^{\vec{i}} = A^{\vec{i}}(B, \vec{i}) \in \{0, 1\}^k$$

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Example: X uniform on  $\{0,1\}^n$  and

$$B = \begin{cases} X & \text{with prob. } 1/2 \\ 0 & \text{with prob. } 1/2 \end{cases}$$

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Notation: Data: X_1, \dots, X_n Exam: \vec{i} = (\vec{i}_1, \dots, \vec{i}_k) with \vec{i}_p \in \{1, \dots, n\} Student memory contains B Answer A^{\vec{i}} = A^{\vec{i}}(B, \vec{i}) \in \{0, 1\}^k Grade G_k(A^{\vec{i}}) = \sum_{p=1}^k \mathbf{1}_{X_{\vec{i}_p} = A_p^{\vec{i}_p}}
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Property we are looking after:

memory *B* allows answering many  $X_1, \ldots, X_n$  correctly

#### Theorem

For any  $P_{X_1...X_nB}$  and any  $\{A^{\vec{i}}\}_{\vec{i}}$ , there exists an  $\overline{A} = \overline{A}(B, \vec{i}, X_{\vec{i}}) \in \{0, 1\}^n$  s.t.

$$\mathbf{P}\left\{\frac{\mathsf{G}_n(\overline{A})}{n} \leqslant \frac{\mathsf{G}_k(A^{\overline{i}})}{k} - \delta\right\} \leqslant e^{-\frac{\delta^2 k}{32}}$$

## Exam: simple strategies

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Student memory contains *B* Answer  $A^{\vec{i}} = A^{\vec{i}}(B, \vec{i}) \in \{0, 1\}^k$ 

For simple strategies,  $A_p^{\vec{i}} = A_{\vec{i}_p}$  for some  $A \in \{0, 1\}^n$ 

We choose  $\overline{A} = A$ . Statement becomes

#### **Theorem**

For any random variable  $A = A_1 \dots A_n$ ,

$$\mathbf{P}_{\vec{i},X,A} \left\{ \frac{1}{n} \sum_{\ell=1}^{n} \mathbf{1}_{X_{\ell} = A_{\ell}} \leqslant \frac{1}{k} \sum_{p=1}^{k} \mathbf{1}_{X_{\vec{i}_p} = A_{\vec{i}_p}} - \delta \right\} \leqslant e^{-\frac{\delta^2 k}{32}}$$

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For fixed *X* and *A*: standard bounds on hypergeometric distribution

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$$\overline{A}_{\ell} = \text{maj}\{A_{\ell}^{\vec{j}} : \ell \in \vec{j}\}$$

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How to choose  $\overline{A}$ ?

• Choose  $\overline{A}_{\ell} = \text{MAJ}\{A_{\ell}^{\vec{j}} : \ell \in \vec{j}\}\$  does not work, have to use  $\vec{i}$ 

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- Optimal strategy? In what sense?

Notation: 
$$\vec{i}^{p-1} = \vec{i}_1, \dots, \vec{i}_{p-1}$$

### Two steps:

- Introduce "sequential exams" and prove statement
- Relate general strategies for a strategy for sequential exam

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### Sequential exam (or oral exam)

Interaction between examiner and student

- Questions one by one
- Have to answer  $\vec{i}_p$  before getting  $\vec{i}_{p+1}$
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Remark: A priori "general" and "sequential" incomparable

# Proof for sequential strategies

#### Theorem

For any sequential strategy  $A^{\text{seq}}$ , there exists an  $\overline{A} = \overline{A}(B, \vec{i}, X_{\vec{i}})$  such that

$$\mathbf{P}\left\{\frac{\mathsf{G}_n(\overline{A})}{n} \leqslant \frac{\mathsf{G}_k(A^{\vec{i}})}{k} - \delta\right\} \leqslant e^{-\frac{\delta^2 k}{8}}$$

Simplification: define  $\overline{A}$  only on  $\vec{j}$  with  $|\vec{j}| = k$ 

$$\rightarrow$$
 look at  $\left[\frac{G_k(\overline{A})}{k} \leqslant \frac{G_k(A^{\text{seq}})}{k} - \delta\right]$ 

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$$\overline{A}_{\vec{j}_p} \stackrel{\text{def}}{=} A_p^{\text{seq}}(\vec{j}_p, \vec{i}^{p-1}, X_{\vec{i}^{p-1}})$$

*To answer all questions:* Partition  $[n] = S_1 \cup \cdots \cup S_k$  at random, and for  $\ell \in S_p$ , let  $\overline{A}_{\ell} = A^{\text{seq}}(\ell, \overline{\ell}^{p-1}, X_{\overline{\ell}^{p-1}})$ 

## Proof for sequential strategies

**Notation:**  $\vec{i}^{p-1} = \vec{i}_1, \dots, \vec{i}_{p-1}$  Grade  $\mathsf{G}_k(A^{\mathrm{seq}}) = \sum_{p=1}^k \mathbf{1}_{X_{\overrightarrow{i}_p} = A_p}$  Grade  $\mathsf{G}_k(\overline{A}) = \sum_{p=1}^k \mathbf{1}_{X_{\overrightarrow{i}_p} = \overline{A}_p}$ 

Using Azuma's inequality:

$$\mathbf{P}\left\{\sum_{p=1}^{k}\mathbf{1}_{X_{\vec{i}_p}=A_p^{\text{seq}}}-\sum_{p=1}^{k}\mathbf{E}_{\vec{i}_p,X_{\vec{i}_p}}\left\{\mathbf{1}_{X_{\vec{i}_p}=A_p^{\text{seq}}}\middle|\vec{i}^{p-1}\vec{j}^{p-1}X_{\vec{i}^{p-1}}X_{\vec{j}^{p-1}}\right\}\geqslant \delta k\right\}\leqslant e^{-\frac{\delta^2k}{2}}$$

$$\mathbf{P}\left\{\sum_{p=1}^{k}\mathbf{E}_{\vec{j}_{p},X_{\vec{j}_{p}}}\left\{\mathbf{1}_{X_{\vec{j}_{p}}=\overline{A}_{p}}\left|\vec{i}^{p-1}\vec{j}^{p-1}X_{\vec{j}^{p}-1}X_{\vec{j}^{p-1}}\right.\right\}-\sum_{p=1}^{k}\mathbf{1}_{X_{\vec{j}_{p}}=\overline{A}_{p}}\geqslant\delta k\right\}\leqslant e^{-\frac{\delta^{2}k}{2}}$$

Observe:

$$\mathbf{E}\left\{\mathbf{1}_{X_{\vec{i}p}=A_{p}^{\text{seq}}}\middle|\vec{i}^{p-1}\vec{j}^{p-1}X_{\vec{i}^{p-1}}X_{\vec{j}^{p-1}}X_{\vec{j}^{p-1}}\right\} = \mathbf{E}\left\{\mathbf{1}_{X_{\vec{j}p}=\overline{A}_{p}}\middle|\vec{i}^{p-1}\vec{j}^{p-1}X_{\vec{i}^{p-1}}X_{\vec{j}^{p-1}}\right\}$$

$$\Rightarrow \qquad \mathbf{P}\left\{\sum_{p=1}^{k}\mathbf{1}_{X_{\vec{l}p}=A_{p}^{\text{seq}}}-\sum_{p=1}^{k}\mathbf{1}_{X_{\vec{l}p}=\overline{A}_{p}}\geqslant 2\delta k\right\}\leqslant 2e^{-\frac{\delta^{2}k}{2}}$$

# Relating general to sequential strategies

#### Theorem

There exists  $A^{\text{seq}}$  such that for any  $\{A^{\vec{i}}\}_{\vec{i}}$ 

$$\mathbf{P}\left\{\sum_{p=1}^{k}\mathbf{1}_{X_{\vec{i}_{p}}=A_{p}^{\vec{i}}}-\sum_{p=1}^{k}\mathbf{1}_{X_{\vec{i}_{p}}=A_{p}^{\text{seq}}}\geqslant\delta k\right\}\leqslant e^{-\frac{\delta^{2}k}{8}}$$

$$A^{\text{seq}}(\ell, \vec{i}^{p-1}, X_{\vec{i}^{p-1}}) \stackrel{\text{def}}{=} \text{best guess for } X_{\ell} \text{ given } B, \vec{i}^{p-1}, X_{\vec{i}^{p-1}}$$

Azuma 
$$\Rightarrow \sum_{p=1}^{k} \mathbf{1}_{X_{\vec{i}_p} = A_p^{\vec{i}}} \approx \sum_{p=1}^{k} \mathbf{E}_{\vec{i}_p, X_{\vec{i}_p}} \left\{ \mathbf{1}_{X_{\vec{i}_p} = A_p^{\vec{i}}} \middle| \vec{t}^{p-1} X_{\vec{i}^{p-1}} (A^{\vec{i}})^{p-1} \right\}$$

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For any fixed  $\vec{i}_p$  and B,  $(A^{\vec{i}})^{p-1}$  cannot help in predicting  $X_{\vec{i}}$ .

$$\Longrightarrow \mathbf{E}_{\vec{i}_p, X_{\vec{i}_p}} \left\{ \mathbf{1}_{X_{\vec{i}_p} = A_p^{\text{seq}}} \middle| \vec{i}^{p-1} X_{\vec{i}^{p-1}} (A^{\vec{i}})^{p-1} \right\} \geqslant \mathbf{E}_{\vec{i}_p, X_{\vec{i}_p}} \left\{ \mathbf{1}_{X_{\vec{i}_p} = A_p^{\vec{i}}} \middle| \vec{i}^{p-1} X_{\vec{i}^{p-1}} (A^{\vec{i}})^{p-1} \right\}_{11/13}$$

# Recap of the proof

Start with  $\{A^{\vec{i}}\}_{\vec{i}}$ 

 $A^{\rm seq}$  (guesses optimally given past) is at least as good on exam  $\vec{i}$ . If  $A^{\rm seq}$  works on  $\vec{i}$ , also works on rest

#### Theorem

For any strategy  $\{A^{\vec{i}}\}_{\vec{i}}$ , there exists an  $\overline{A} = \overline{A}(B, \vec{i}, X_{\vec{i}})$  such that

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## Quantum student B

System *B* is quantum

Important difficulty: Applying  $A^{\vec{i}}(B, \vec{i})$  affects B Issues in the two steps of the classical proof

- For sequential strategies, measurement may lead to losses
- Cannot simultaneously define the two strategies

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### Better way of quantifying correlation:

• Use  $H_{\max}(X_1 ... X_n | B)$  (number of bits of hint for perfect recovery of  $X_1 ... X_n$ )