

CS151 Complexity Theory

Lecture 2
April 4, 2019

Interlude

- In an ideal world, given language L
 - state an algorithm deciding L
 - **prove** that no algorithm does better
- we are pretty good at part 1
- we are currently **completely helpless** when it comes to part 2, for most problems that we care about

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Interlude

- in place of part 2 we can
 - relate the difficulty of problems to each other via **reductions**
 - prove that a problem is a “hardest” problem in a complexity class via **completeness**
- powerful, successful surrogate for lower bounds

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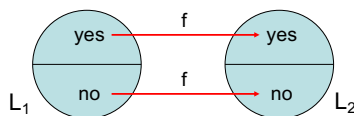
Reductions

- **reductions** are the main tool for relating problems to each other
- given two languages L_1 and L_2 we say “ L_1 reduces to L_2 ” and we write “ $L_1 \leq L_2$ ” to mean:
 - there exists an efficient (for now, poly-time) algorithm that computes a function f s.t.
 - $x \in L_1$ implies $f(x) \in L_2$
 - $x \notin L_1$ implies $f(x) \notin L_2$

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Reductions

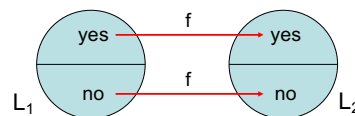


- **positive use:** given new problem L_1 reduce it to L_2 that we know to be in \mathbf{P} . Conclude L_1 in \mathbf{P} (how?)
 - e.g. bipartite matching \leq max flow
 - formalizes “ L_1 as easy as L_2 ”

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Reductions



- **negative use:** given new problem L_2 reduce L_1 (that we believe not to be in \mathbf{P}) to it. Conclude L_2 *not* in \mathbf{P} if L_1 *not* in \mathbf{P} (how?)
 - e.g. satisfiability \leq graph 3-coloring
 - formalizes “ L_2 as hard as L_1 ”

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Reductions

- Example reduction:
 - 3SAT = { ϕ : ϕ is a 3-CNF Boolean formula that has a satisfying assignment }
(3-CNF = AND of OR of ≤ 3 literals)
 - IS = { (G, k) | G is a graph with an independent set $V' \subseteq V$ of size $\geq k$ }
(ind. set = set of vertices no two of which are connected by an edge)

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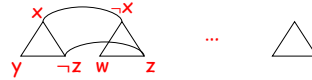
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Ind. Set is NP-complete

The reduction f : given

$$\phi = (x \vee y \vee \neg z) \wedge (\neg x \vee w \vee z) \wedge \dots \wedge (\dots)$$

we produce graph G_ϕ :



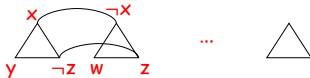
- one triangle for each of m clauses
- edge between every pair of contradictory literals
- set $k = m$

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Reductions

$$\phi = (x \vee y \vee \neg z) \wedge (\neg x \vee w \vee z) \wedge \dots \wedge (\dots)$$



- Claim: ϕ has a satisfying assignment if and only if G has an independent set of size at least k
 - proof?
- Conclude that 3SAT \leq IS.

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Completeness

- complexity class \mathbf{C}
- language L is **C-complete** if
 - L is in \mathbf{C}
 - every language in \mathbf{C} reduces to L
- very important concept
- formalizes “ L is hardest problem in complexity class \mathbf{C} ”

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Completeness

- Completeness allows us to reason about the entire class by thinking about a single concrete problem
- related concept: language L is **C-hard** if
 - every language in \mathbf{C} reduces to L

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Completeness

- May ask: how to show every language in \mathbf{C} reduces to L ?
 - in practice, shown by reducing **known C-complete** problem to L
 - often not hard to find “1st” C-complete language, but it might not be “natural”

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Completeness

- Example:
 - NP** = the set of languages L where

$$L = \{ x : \exists y, |y| \leq |x|^k, (x, y) \in R \}$$
 and R is a language in **P**.
 - one **NP**-complete language "bounded halting":

$$BH = \{ (M, x, 1^k, 1^m) : \exists y, |y| \leq |x|^k \text{ s.t. } M \text{ accepts } (x, y) \text{ in at most } m \text{ steps} \}$$
- challenge is to find **natural** complete problem
- Cook 71 : 3-SAT **NP**-complete

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Summary

- problems
 - function, decision
 - language = set of strings
- complexity class = set of languages
- efficient computation identified with efficient computation on Turing Machine
 - single-tape, multi-tape
 - diagonalization technique: HALT undecidable
- **TIME** and **SPACE** classes
- reductions
- **C**-completeness, **C**-hardness

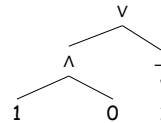
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Time and Space

A motivating question:

- Boolean formula with n nodes
- evaluate using $O(\log n)$ space?



- depth-first traversal requires storing intermediate values
- idea: short-circuit ANDs and ORs when possible

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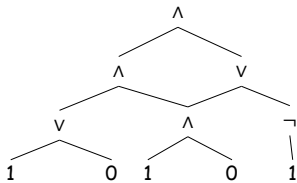
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Time and Space

- Can we evaluate an n node Boolean **circuit** using $O(\log n)$ space?



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Time and Space

- Recall:
 - **TIME**(f(n)), **SPACE**(f(n))
- Questions:
 - how are these classes related to each other?
 - how do we define **robust** time and space classes?
 - what problems are contained in these classes? complete for these classes?

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Outline

- Why big-oh? Linear Speedup Theorem
- Hierarchy Theorems
- Robust Time and Space Classes
- Relationships between classes
- Some complete problems

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Linear Speedup

Theorem: Suppose TM M decides language L in time $f(n)$. Then for any $\epsilon > 0$, there exists TM M' that decides L in time

$$\epsilon f(n) + n + 2.$$

- Proof:
 - simple idea: increase “word length”
 - M' will have
 - one more tape than M
 - m -tuples of symbols of M
 - many more states

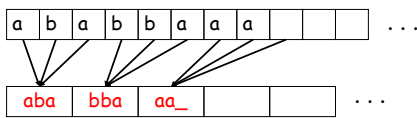
$$\Sigma_{\text{new}} = \Sigma_{\text{old}} \cup \Sigma_{\text{old}}^m$$

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Linear Speedup

- part 1: compress input onto fresh tape

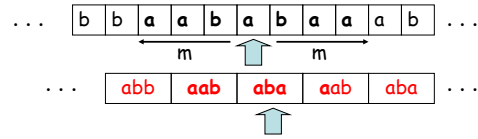


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Linear Speedup

- part 2: simulate M , m steps at a time



- 4 (L,R,R,L) steps to read relevant symbols, “remember” in state
- 2 (L,R or R,L) to make M 's changes

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Linear Speedup

- accounting:
 - part 1 (copying): $n + 2$ steps
 - part 2 (simulation): $6(f(n)/m)$
 - set $m = 6/\epsilon$
 - total: $\epsilon f(n) + n + 2$

Theorem: Suppose TM M decides language L in space $f(n)$. Then for any $\epsilon > 0$, there exists TM M' that decides L in space $\epsilon f(n) + 2$.

- Proof: same.

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Time and Space

- Moral: big-oh notation **necessary** given our model of computation
 - Recall: $f(n) = O(g(n))$ if there exists c such that $f(n) \leq c g(n)$ for all sufficiently large n .
 - TM model incapable of making distinctions between time and space usage that differs by a constant.
- In general: interested in course distinctions not affected by model
 - e.g. simulation of k -string TM running in time $f(n)$ by single-string TM running in time $O(f(n)^2)$

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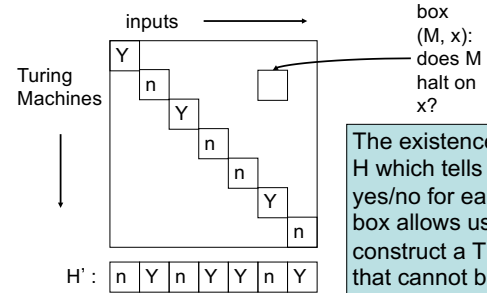
Hierarchy Theorems

- Does **genuinely** more time permit us to decide new languages?
- how can we construct a language L that is *not* in $\text{TIME}(f(n))$...
 - idea: same as “HALT undecidable” diagonalization and simulation

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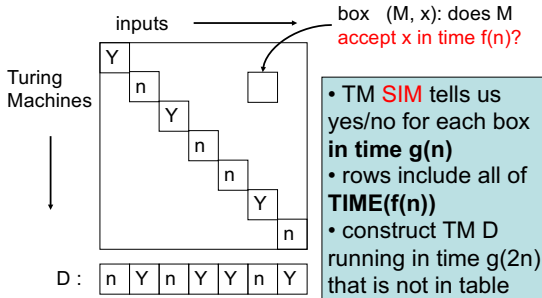
Recall proof for Halting Problem



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Time Hierarchy Theorem



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Time Hierarchy Theorem

Theorem (Time Hierarchy Theorem): For every proper complexity function $f(n) \geq n$:

$$\text{TIME}(f(n)) \subsetneq \text{TIME}(f(2n)^3).$$

- more on “proper complexity functions” later...

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Proof of Time Hierarchy Theorem

- Proof:
 - SIM is TM deciding language $\{ \langle M, x \rangle : M \text{ accepts } x \text{ in } \leq f(|x|) \text{ steps} \}$
 - Claim: SIM runs in time $g(n) = f(n)^3$.
 - define new TM D : on input $\langle M \rangle$
 - if SIM accepts $\langle M, M \rangle$, reject
 - if SIM rejects $\langle M, M \rangle$, accept
 - D runs in time $g(2n)$

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Proof of Time Hierarchy Theorem

- Proof (continued):
 - suppose M in $\text{TIME}(f(n))$ decides $L(D)$
 - $M(\langle M \rangle) = \text{SIM}(\langle M, M \rangle) \neq D(\langle M \rangle)$
 - but $M(\langle M \rangle) = D(\langle M \rangle)$
 - contradiction.

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Proof of Time Hierarchy Theorem

- Claim: there is a TM SIM that decides $\{ \langle M, x \rangle : M \text{ accepts } x \text{ in } \leq f(|x|) \text{ steps} \}$ and runs in time $g(n) = f(n)^3$.
- Proof sketch: SIM has 4 work tapes
 - contents and “virtual head” positions for M’s tapes
 - M’s transition function and state
 - $f(|x|)$ “+”s used as a clock
 - scratch space

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Proof of Time Hierarchy Theorem

- contents and “virtual head” positions for M’s tapes
- M’s transition function and state
- $f(|x|)$ “+”s used as a clock
- scratch space
- initialize tapes
- simulate step of M, advance head on tape 3; repeat.
- can check running time is as claimed.
- Important detail: need to initialize tape 3 in time $O(f(n))$

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Proper Complexity Functions

- Definition: f is a **proper complexity function** if
 - $f(n) \geq f(n-1)$ for all n
 - there exists a TM M that outputs exactly $f(n)$ symbols on input 1^n , and runs in time $O(f(n) + n)$ and space $O(f(n))$.

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Proper Complexity Functions

- includes all reasonable functions we will work with
 - $\log n, \sqrt{n}, n^2, 2^n, n!, \dots$
 - if f and g are proper then $f + g, fg, f(g), f^g, 2^g$ are all proper
- can mostly ignore, but be aware it is a genuine concern:
- **Theorem:** \exists **non-proper** f such that $\text{TIME}(f(n)) = \text{TIME}(2^{f(n)})$.

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Hierarchy Theorems

- Does **genuinely** more **space** permit us to decide new languages?

Theorem (Space Hierarchy Theorem): For every proper complexity function $f(n) \geq \log n$:

$$\text{SPACE}(f(n)) \subsetneq \text{SPACE}(f(n) \log f(n)).$$

- Proof: same ideas.

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Robust Time and Space Classes

- What is meant by “robust” class?
 - no formal definition
 - reasonable changes to model of computation shouldn’t change class
 - should allow “modular composition” – calling subroutine in class (for classes closed under complement...)

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Robust Time and Space Classes

- Robust time and space classes:

$$L = \text{SPACE}(\log n)$$

$$\text{PSPACE} = \cup_k \text{SPACE}(n^k)$$

$$P = \cup_k \text{TIME}(n^k)$$

$$\text{EXP} = \cup_k \text{TIME}(2^{n^k})$$

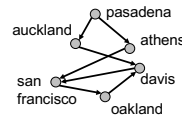
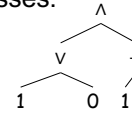
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Time and Space Classes

- Problems in these classes:

L: FVAL, integer multiplication, most reductions...



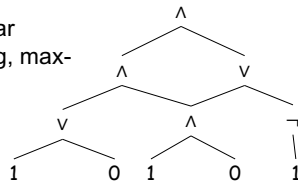
PSPACE: generalized geography, 2-person games...

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Time and Space Classes

P: CVAL, linear programming, max-flow...



EXP: SAT, all of NP and much more...

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Relationships between classes

- How are these four classes related to each other?

- Time Hierarchy Theorem implies

$$P \subsetneq \text{EXP}$$

$$- P \subseteq \text{TIME}(2^n) \subsetneq \text{TIME}(2^{(2n)^3}) \subseteq \text{EXP}$$

- Space Hierarchy Theorem implies

$$L \subsetneq \text{PSPACE}$$

$$- L = \text{SPACE}(\log n) \subsetneq \text{SPACE}(\log^2 n) \subseteq \text{PSPACE}$$

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Relationships between classes

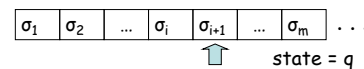
- Easy: $P \subseteq \text{PSPACE}$
- L vs. P, PSPACE vs. EXP ?

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Relationships between classes

- Useful convention: **Turing Machine configurations**. Any point in computation



represented by string:

$$C = \sigma_1 \sigma_2 \dots \sigma_i q \sigma_{i+1} \sigma_{i+2} \dots \sigma_m$$

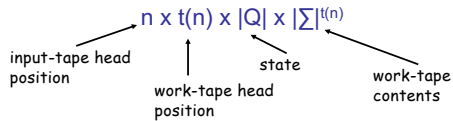
- start configuration for single-tape TM on input x : $q_{\text{start}} X_1 X_2 \dots X_n$

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Relationships between classes

- easy to tell if C **yields** C' in 1 step
- **configuration graph**: nodes are configurations, edge (C, C') iff C **yields** C' in one step
- # configurations for a 2-tape TM (work tape + read-only input) that runs in **space** t(n)



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Relationships between classes

- if $t(n) = c \log n$, at most

$$n \times (c \log n) \times c_0 \times c_1^{c \log n} \leq n^k$$
 configurations.
- can determine if reach q_{accept} or q_{reject} from start configuration by exploring config. graph of size n^k (e.g. by DFS)
- Conclude: **L ⊆ P**

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Relationships between classes

- if $t(n) = n^c$, at most

$$n \times n^c \times c_0 \times c_1^{n^c} \leq 2^{n^k}$$
 configurations.
- can determine if reach q_{accept} or q_{reject} from start configuration by exploring config. graph of size 2^{n^k} (e.g. by DFS)
- Conclude: **PSPACE ⊆ EXP**

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Relationships between classes

- So far:

$$\mathbf{L} \subseteq \mathbf{P} \subseteq \mathbf{PSPACE} \subseteq \mathbf{EXP}$$
- believe all containments strict
- know $\mathbf{L} \subsetneq \mathbf{PSPACE}$, $\mathbf{P} \subsetneq \mathbf{EXP}$
- even before any mention of NP, two **major** unsolved problems:

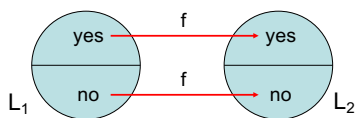
$$\mathbf{L} \stackrel{?}{=} \mathbf{P} \quad \mathbf{P} \stackrel{?}{=} \mathbf{PSPACE}$$

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A P-complete problem

- We don't know how to prove $\mathbf{L} \neq \mathbf{P}$
- But, can identify problems in **P** **least likely** to be in **L** using **P**-completeness.
- need stronger notion of reduction (why?)



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A P-complete problem

- **logspace reduction**: f computable by TM that uses $O(\log n)$ space
 - denoted " $L_1 \leq_L L_2$ "
- If L_2 is **P**-complete, then L_2 in **L** implies $\mathbf{L} = \mathbf{P}$ (homework problem)

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A P-complete problem

- **Circuit Value (CVAL):** given a variable-free Boolean circuit (gates $\wedge, \vee, \neg, 0, 1$), does it output 1?

Theorem: CVAL is P-complete.

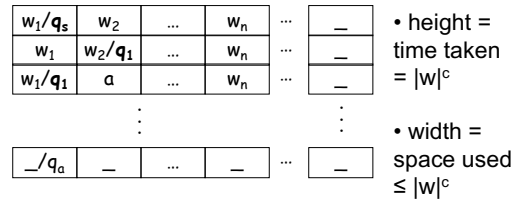
- Proof:
 - already argued in P
 - L arbitrary language in P, TM M decides L in n^c steps

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A P-complete problem

- **Tableau** (configurations written in an array) for machine M on input w:

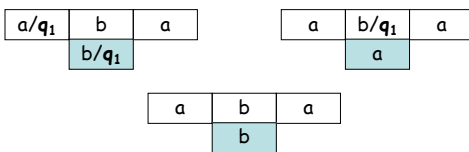


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A P-complete problem

- Important observation: contents of cell in tableau determined by 3 others above it:

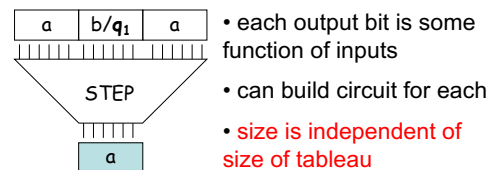


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A P-complete problem

- Can build Boolean circuit STEP
 - input (binary encoding of) 3 cells
 - output (binary encoding of) 1 cell



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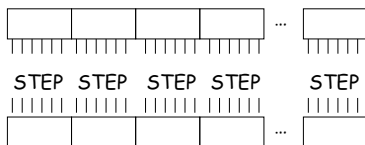
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A P-complete problem

Tableau for M on input w

w_1/q_s	w_2	...	w_n	...	—
w_1	w_2/q_1	...	w_n	...	—

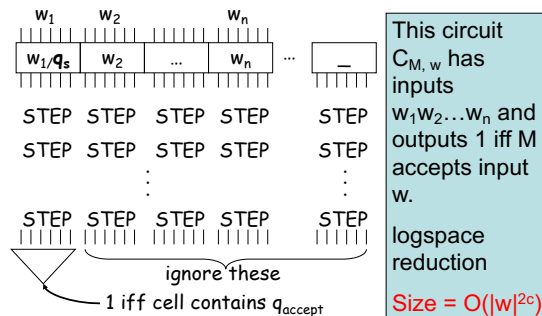
- $|w|^c$ copies of STEP compute row i from i-1



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A P-complete problem



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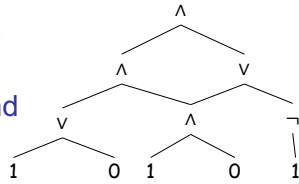
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Answer to question

- Can we evaluate an n node Boolean **circuit** using $O(\log n)$ space?

- **NO!** (probably)

- **CVAL in L if and only if L = P**



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Padding and succinctness

Two consequences of measuring running time as function of input length:

- “padding”
 - suppose $L \in \mathbf{EXP}$, and define
$$\mathbf{PAD}_L = \{x\#^N : x \in L, N = 2^{|x|^k}\}$$
 - TM that decides \mathbf{PAD}_L : ensure suffix of N #s, ignore #s, then simulate TM that decides L
 - running time now polynomial !

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