
Constructing Equiangular Tight Frames with Alternating Projection



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Equiangular Tight Frames



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Equiangular Tight Frames



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- A lower bound on the maximum correlation between a pair of vectors:

$$\max_{j \neq k} |\langle \mathbf{s}_j, \mathbf{s}_k \rangle| \geq \sqrt{\frac{N-d}{d(N-1)}} \stackrel{\text{def}}{=} \mu(d, N)$$

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- The bound is met if and only if
 1. The vectors are equiangular
 2. The vectors form a tight frame

Tight Frames vs. Equiangular Tight Frames



Tight frame:

$$\begin{bmatrix} 1.0000 & 0.2414 & -0.6303 & 0.5402 & -0.3564 & -0.3543 \\ 0.2414 & 1.0000 & -0.5575 & -0.4578 & 0.5807 & -0.2902 \\ -0.6303 & -0.5575 & 1.0000 & 0.2947 & 0.3521 & -0.2847 \\ 0.5402 & -0.4578 & 0.2947 & 1.0000 & -0.2392 & -0.5954 \\ -0.3564 & 0.5807 & 0.3521 & -0.2392 & 1.0000 & -0.5955 \\ -0.3543 & -0.2902 & -0.2847 & -0.5954 & -0.5955 & 1.0000 \end{bmatrix}$$

Equiangular tight frame:

$$\begin{bmatrix} 1.0000 & 0.4472 & -0.4472 & 0.4472 & -0.4472 & -0.4472 \\ 0.4472 & 1.0000 & -0.4472 & -0.4472 & 0.4472 & -0.4472 \\ -0.4472 & -0.4472 & 1.0000 & 0.4472 & 0.4472 & -0.4472 \\ 0.4472 & -0.4472 & 0.4472 & 1.0000 & -0.4472 & -0.4472 \\ -0.4472 & 0.4472 & 0.4472 & -0.4472 & 1.0000 & -0.4472 \\ -0.4472 & -0.4472 & -0.4472 & -0.4472 & -0.4472 & 1.0000 \end{bmatrix}$$

The Gram Matrix



- Suppose $\{\mathbf{s}_j\}$ is an N -vector equiangular tight frame for \mathbb{F}^d
- Its *Gram matrix* G has entries

$$g_{jk} = \langle \mathbf{s}_k, \mathbf{s}_j \rangle$$

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 4. Two eigenvalues: (N/d) with multiplicity d and zero
- Suppose G has Properties 1–4. Then $G = S^*S$, where the columns of S form an N -vector equiangular tight frame for \mathbb{F}^d

Constraint Sets



Define the *structural constraint set*

$$\mathcal{H} \stackrel{\text{def}}{=} \{H \in \mathbb{F}^{N \times N} : H = H^*, \quad \text{diag } H = \mathbf{e}, \quad \text{and} \\ |h_{jk}| \leq \mu \text{ for } j \neq k\}$$

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• Define the *spectral constraint set*

$$\mathcal{G} \stackrel{\text{def}}{=} \{G \in \mathbb{F}^{N \times N} : \boldsymbol{\lambda}(G) = [\underbrace{N/d \dots N/d}_d \ 0 \ \dots \ 0]^T \}$$

Constraint Sets



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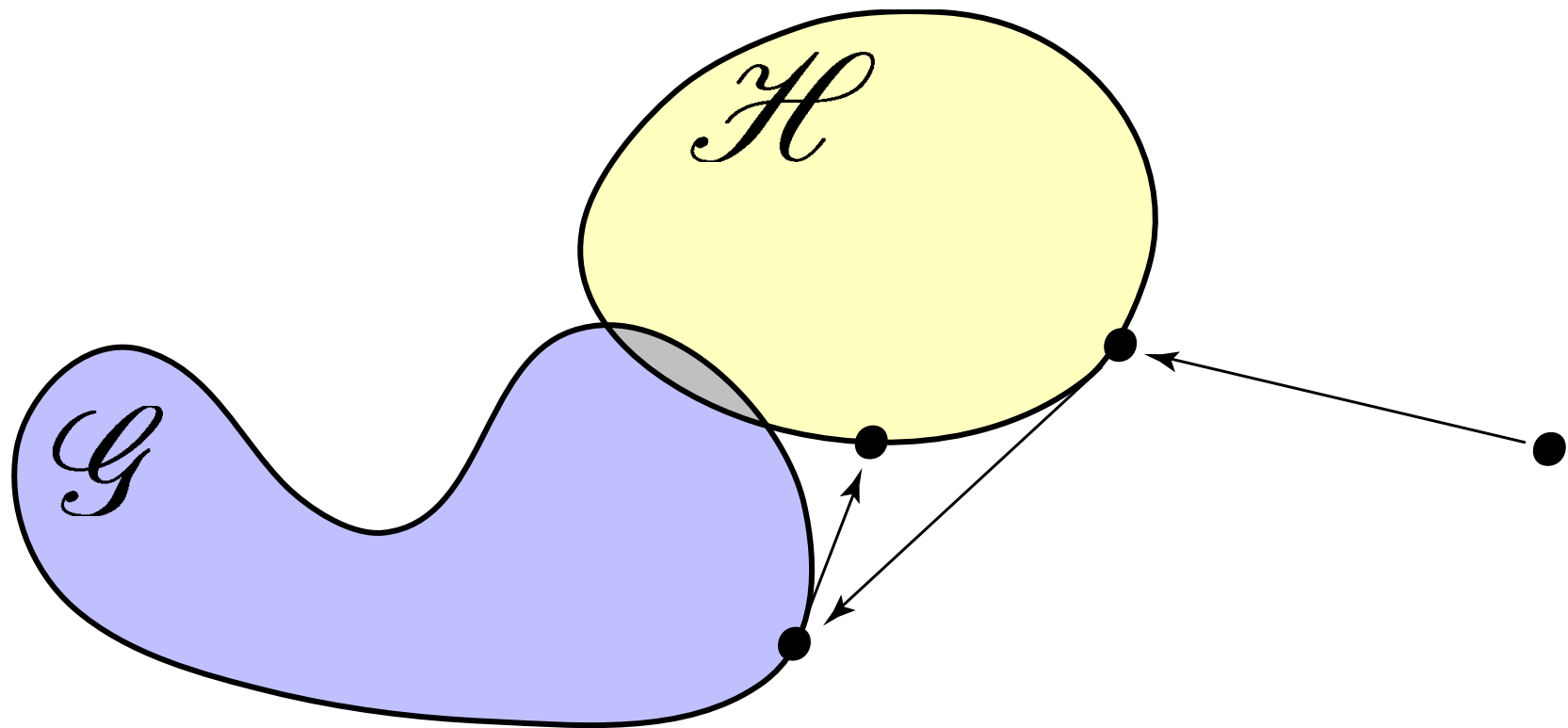
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Goal: Find a matrix in $\mathcal{G} \cap \mathcal{H}$

Alternating Projection



Matrix Nearness Problems



Proposition 1. *Let G be an Hermitian matrix. With respect to Frobenius norm, the unique matrix in \mathcal{H} closest to G has a unit diagonal and off-diagonal entries that satisfy*

$$h_{mn} = \begin{cases} g_{mn} & \text{if } |g_{mn}| \leq \mu, \text{ and} \\ \mu g_{mn} / |g_{mn}| & \text{otherwise.} \end{cases}$$

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Proposition 2. *Let H be an Hermitian matrix whose eigenvalue decomposition is $\sum_{n=1}^N \lambda_n \mathbf{u}_n \mathbf{u}_n^*$ with the eigenvalues decreasingly ordered. With respect to Frobenius norm, a matrix in \mathcal{G} closest to H is given by*

$$(N/d) \sum_{n=1}^d \mathbf{u}_n \mathbf{u}_n^*.$$

Global Convergence



Theorem 1. *Suppose that alternating projection generates an (infinite) sequence of iterates $\{(G_t, H_t)\}$. The sequence has at least one accumulation point.*

✪ *Every accumulation point lies in $\mathcal{G} \times \mathcal{H}$.*

✪ *Every accumulation point (\bar{G}, \bar{H}) satisfies*

$$\|\bar{G} - \bar{H}\|_F = \lim_{t \rightarrow \infty} \|G_t - H_t\|_F.$$

✪ *Every accumulation point (\bar{G}, \bar{H}) satisfies*

$$\|\bar{G} - \bar{H}\|_F = \text{dist}(\bar{G}, \mathcal{H}) = \text{dist}(\bar{H}, \mathcal{G}).$$

Local Convergence



Theorem 2. *In addition, suppose there is an iteration T during which $\|G_T - H_T\|_F < N/(d\sqrt{2})$. We may conclude that*

- *The accumulation point (\bar{G}, \bar{H}) is a fixed point of the algorithm.*
- *The component sequences are asymptotically regular, i.e.,*

$$\|G_{t+1} - G_t\|_F \rightarrow 0 \quad \text{and} \quad \|H_{t+1} - H_t\|_F \rightarrow 0.$$

- **Either** *the component sequences both converge in norm,*

$$\|G_t - \bar{G}\|_F \rightarrow 0 \quad \text{and} \quad \|H_t - \bar{H}\|_F \rightarrow 0,$$

or *the set of accumulation points forms a continuum.*

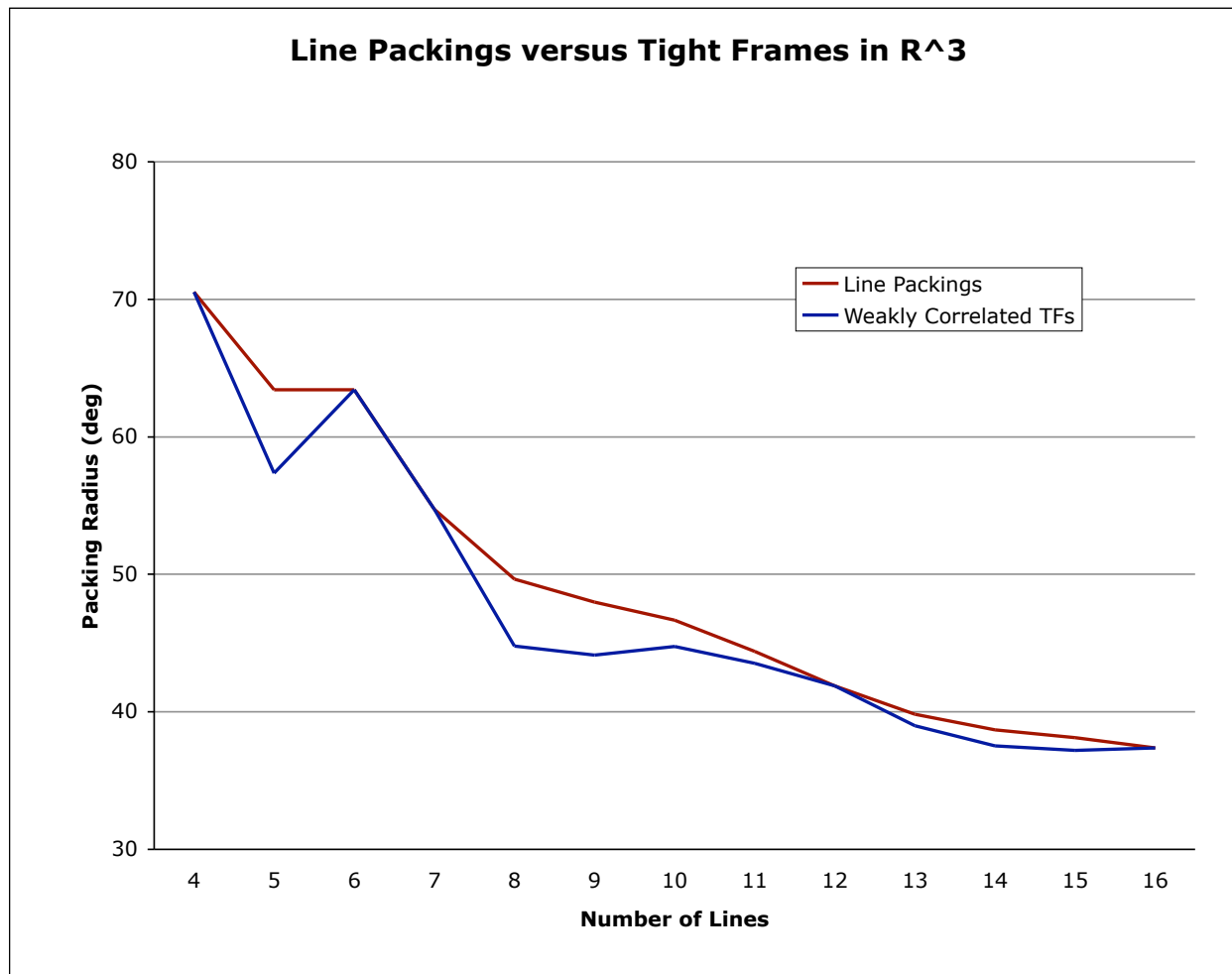
Experimental Results



N	2	3	d		
			4	5	6
3	R	R
4	C	R	R
5	..	.	R	R	..
6	..	R	.	R	R
7	..	C	C	.	R
8	..	.	C	.	.
9	..	C	.	.	C
10	R	.
11	C	C
12	C
13	C	.	.
14
15
16	C	.	R
17
18
19

N	2	3	d		
			4	5	6
20
21	C	.
22
23
24
25	C	.
26
27
28
29
30
31	C
32
33
34
35
36	C

Weakly Correlated Tight Frames



Packing in Projective Spaces



$\mathbb{P}^2(\mathbb{R})$

N	PACKING RADII (DEGREES)		
	JAT	NJAS	Difference
4	70.53	70.53	0.00
5	63.43	63.43	0.00
6	63.43	63.43	0.00
7	54.74	54.74	0.00
8	49.64	49.64	0.00
9	47.98	47.98	0.00
10	46.67	46.67	0.00
11	44.40	44.40	0.00
12	41.88	41.88	0.00
13	39.81	39.81	0.00
14	38.52	38.68	0.17
15	37.93	38.13	0.20
16	37.36	37.38	0.02
17	35.00	35.24	0.23
18	34.22	34.41	0.19
19	32.93	33.21	0.28
20	32.48	32.71	0.23

$\mathbb{P}^3(\mathbb{R})$

N	PACKING RADII (DEGREES)		
	JAT	NJAS	Difference
5	75.52	75.52	0.00
6	70.53	70.53	0.00
7	67.02	67.02	0.00
8	65.53	65.53	0.00
9	64.26	64.26	0.00
10	64.26	64.26	0.00
11	60.00	60.00	0.00
12	60.00	60.00	0.00
13	55.46	55.46	0.00
14	53.63	53.84	0.21
15	52.07	52.50	0.43
16	50.97	51.83	0.85
17	50.66	50.89	0.23
18	50.28	50.46	0.18
19	49.65	49.71	0.06
20	49.11	49.23	0.12
21	48.48	48.55	0.07

Packing in Grassmannian Spaces



$\mathbb{G}(2, \mathbb{R}^4)$, Chordal Distance

N	SQUARED PACKING RADII		
	JAT	NJAS	Difference
3	1.5000	1.5000	0.0000
4	1.3333	1.3333	0.0000
5	1.2500	1.2500	0.0000
6	1.2000	1.2000	0.0000
7	1.1656	1.1667	0.0011
8	1.1423	1.1429	0.0005
9	1.1226	1.1231	0.0004
10	1.1111	1.1111	0.0000
11	0.9981	1.0000	0.0019
12	0.9990	1.0000	0.0010
13	0.9996	1.0000	0.0004
14	1.0000	1.0000	0.0000
15	1.0000	1.0000	0.0000
16	0.9999	1.0000	0.0001
17	1.0000	1.0000	0.0000
18	0.9992	1.0000	0.0008

$\mathbb{G}(2, \mathbb{R}^5)$, Chordal Distance

N	SQUARED PACKING RADII		
	JAT	NJAS	Difference
3	1.7500	1.7500	0.0000
4	1.6000	1.6000	0.0000
5	1.5000	1.5000	0.0000
6	1.4400	1.4400	0.0000
7	1.4000	1.4000	0.0000
8	1.3712	1.3714	0.0002
9	1.3464	1.3500	0.0036
10	1.3307	1.3333	0.0026
11	1.3069	1.3200	0.0131
12	1.2973	1.3064	0.0091
13	1.2850	1.2942	0.0092
14	1.2734	1.2790	0.0056
15	1.2632	1.2707	0.0075
16	1.1838	1.2000	0.0162
17	1.1620	1.2000	0.0380
18	1.1589	1.1909	0.0319

For more information. . .



Reports

- ✪ JAT with Dhillon, Heath, and Strohmer. *Designing Structured Tight Frames via Alternating Projection*. ICES Report 03-50, December 2003.
- ✪ JAT. *Constructing Packings in Projective Spaces and Grassmannian Spaces via Alternating Projection*. ICES Report 04-23, May 2004.
- ✪ JAT with Dhillon, Heath, M. Sustik. *Necessary Conditions for the Existence of Equiangular Tight Frames*. In preparation, May 2004.

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