
Recent Theoretical Advances in Sparse Approximation



Joel A. Tropp

<jtropp@ices.utexas.edu>

Institute for Computational Engineering and Sciences
The University of Texas at Austin

Includes joint work with A. C. Gilbert, S. Muthukrishnan and M. J. Strauss of AT&T Research. S. Muthukrishnan is also affiliated with Rutgers Univ.

What is Sparse Approximation?



- We work in the finite-dimensional Hilbert space \mathbb{C}^d
- Let $\mathcal{D} = \{\varphi_\omega\}$ be a *dictionary* of N unit-norm *atoms* indexed by Ω
- Let m be a fixed, positive integer
- Suppose x is an *arbitrary* input vector

What is Sparse Approximation?



- We work in the finite-dimensional Hilbert space \mathbb{C}^d
- Let $\mathcal{D} = \{\varphi_\omega\}$ be a *dictionary* of N unit-norm *atoms* indexed by Ω
- Let m be a fixed, positive integer
- Suppose x is an *arbitrary* input vector
- The *sparse approximation problem* is to solve

$$\min_{\Lambda \subset \Omega} \min_{\mathbf{b} \in \mathbb{C}^\Lambda} \left\| x - \sum_{\lambda \in \Lambda} b_\lambda \varphi_\lambda \right\|_2 \quad \text{subject to} \quad |\Lambda| \leq m$$

- The inner minimization is a least squares problem
- But the outer minimization is *combinatorial*

What is Sparse Approximation?



- We work in the finite-dimensional Hilbert space \mathbb{C}^d
- Let $\mathcal{D} = \{\varphi_\omega\}$ be a *dictionary* of N unit-norm *atoms* indexed by Ω
- Let m be a fixed, positive integer
- Suppose x is an *arbitrary* input vector
- The *sparse approximation problem* is to solve

$$\min_{\Lambda \subset \Omega} \min_{\mathbf{b} \in \mathbb{C}^\Lambda} \left\| x - \sum_{\lambda \in \Lambda} b_\lambda \varphi_\lambda \right\|_2 \quad \text{subject to} \quad |\Lambda| \leq m$$

- The inner minimization is a least squares problem
- But the outer minimization is *combinatorial*
- Formally, we call the problem (\mathcal{D}, m) -SPARSE

Basic Dictionary Properties



- The dictionary is *complete* if the atoms span \mathbb{C}^d
- The dictionary is *redundant* if it contains linearly dependent atoms

Basic Dictionary Properties



- The dictionary is *complete* if the atoms span \mathbb{C}^d
- The dictionary is *redundant* if it contains linearly dependent atoms
- A complete dictionary can represent every vector without error
- Each vector has infinitely many representations over a redundant dictionary

Basic Dictionary Properties



- The dictionary is *complete* if the atoms span \mathbb{C}^d
- The dictionary is *redundant* if it contains linearly dependent atoms
- A complete dictionary can represent every vector without error
- Each vector has infinitely many representations over a redundant dictionary
- In most modern applications, dictionaries are complete and redundant

Subset Selection in Regression



- Suppose x is a vector of d observations of a random variable X
- Suppose φ_ω is a vector of d observations of random variable Φ_ω
- Want to find a small subset of $\{\Phi_\omega\}$ for linear prediction of X

Subset Selection in Regression



- Suppose x is a vector of d observations of a random variable X
- Suppose φ_ω is a vector of d observations of random variable Φ_ω
- Want to find a small subset of $\{\Phi_\omega\}$ for linear prediction of X
- *Method:* Solve the sparse approximation problem!

Subset Selection in Regression



- Suppose x is a vector of d observations of a random variable X
- Suppose φ_ω is a vector of d observations of random variable Φ_ω
- Want to find a small subset of $\{\Phi_\omega\}$ for linear prediction of X
- *Method:* Solve the sparse approximation problem!

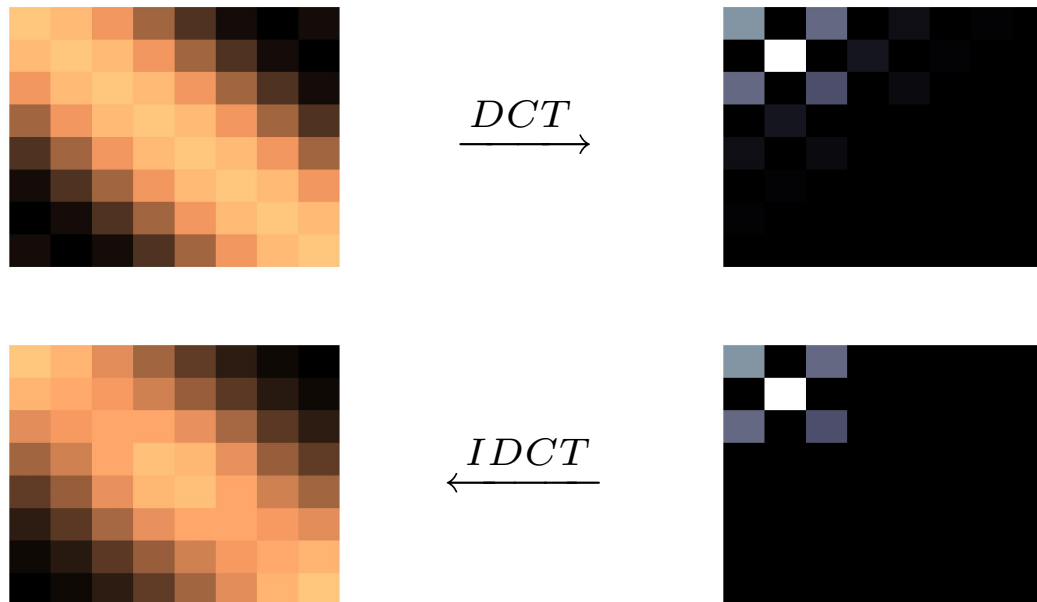
- Statisticians have developed many approaches
 1. Forward selection
 2. Backward elimination
 3. Sequential replacement
 4. Stepwise regression [Efroymson 1960]
 5. Exhaustive search [Garside 1965, Beale et al. 1967]
 6. Projection Pursuit Regression [Friedman–Stuetzle 1981]

Reference: [A. J. Miller 2002]

Transform Coding



🦋 In simplest form, can be viewed as a sparse approximation problem

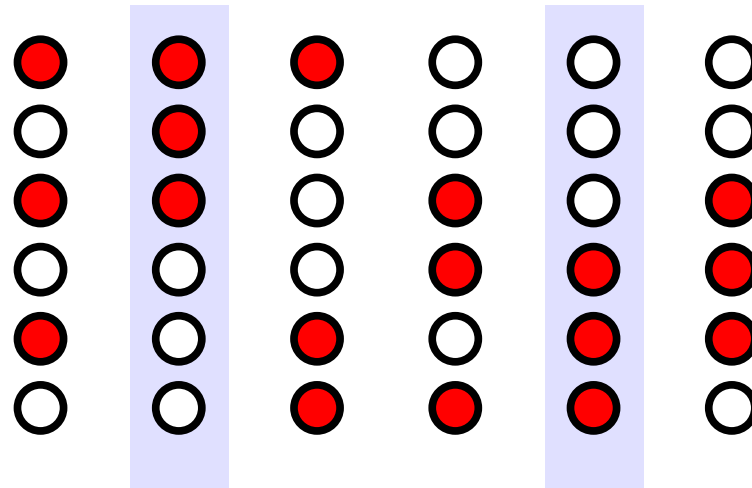


Reference: [Evans-Mersereau 2003]

Computational Complexity



Theorem 1. [Davis (1994), Natarajan (1995)] *Any instance of Exact Cover by Three Sets (X3C) is reducible in polynomial time to a sparse approximation problem.*



An instance of X3C

Computational Complexity II



Corollary 2. *Any algorithm that can solve (\mathcal{D}, m) -SPARSE for every dictionary and sparsity level must solve an NP-hard problem.*

- ✿ It is widely believed that no tractable algorithms exist for NP-hard problems

Computational Complexity II



Corollary 2. *Any algorithm that can solve (\mathcal{D}, m) -SPARSE for every dictionary and sparsity level must solve an NP-hard problem.*

- ✪ It is widely believed that no tractable algorithms exist for NP-hard problems
- ✪ **BUT** a specific problem (\mathcal{D}, m) -SPARSE may be easy
- ✪ **AND** preprocessing is allowed

Orthonormal Dictionaries



• Suppose that \mathcal{D} is an orthonormal basis (ONB)

Orthonormal Dictionaries



- Suppose that \mathcal{D} is an orthonormal basis (ONB)
- For any vector \boldsymbol{x} and sparsity level m ,
 1. Sort the indices $\{\omega_n\}$ so the numbers $|\langle \boldsymbol{x}, \boldsymbol{\varphi}_{\omega_n} \rangle|$ are decreasing

Orthonormal Dictionaries



- Suppose that \mathcal{D} is an orthonormal basis (ONB)
- For any vector \mathbf{x} and sparsity level m ,
 1. Sort the indices $\{\omega_n\}$ so the numbers $|\langle \mathbf{x}, \varphi_{\omega_n} \rangle|$ are decreasing
 2. The solution to (\mathcal{D}, m) -SPARSE for input \mathbf{x} is

$$\sum_{n=1}^m \langle \mathbf{x}, \varphi_{\omega_n} \rangle \varphi_{\omega_n}$$

Orthonormal Dictionaries



- Suppose that \mathcal{D} is an orthonormal basis (ONB)
- For any vector \mathbf{x} and sparsity level m ,
 1. Sort the indices $\{\omega_n\}$ so the numbers $|\langle \mathbf{x}, \varphi_{\omega_n} \rangle|$ are decreasing
 2. The solution to (\mathcal{D}, m) -SPARSE for input \mathbf{x} is

$$\sum_{n=1}^m \langle \mathbf{x}, \varphi_{\omega_n} \rangle \varphi_{\omega_n}$$

3. The squared approximation error is

$$\sum_{n=m+1}^d |\langle \mathbf{x}, \varphi_{\omega_n} \rangle|^2$$

Orthonormal Dictionaries



- Suppose that \mathcal{D} is an orthonormal basis (ONB)
- For any vector \mathbf{x} and sparsity level m ,
 1. Sort the indices $\{\omega_n\}$ so the numbers $|\langle \mathbf{x}, \varphi_{\omega_n} \rangle|$ are decreasing
 2. The solution to (\mathcal{D}, m) -SPARSE for input \mathbf{x} is

$$\sum_{n=1}^m \langle \mathbf{x}, \varphi_{\omega_n} \rangle \varphi_{\omega_n}$$

3. The squared approximation error is

$$\sum_{n=m+1}^d |\langle \mathbf{x}, \varphi_{\omega_n} \rangle|^2$$

Insight: (\mathcal{D}, m) -SPARSE can be solved approximately so long as sub-collections of m atoms in \mathcal{D} are sufficiently close to being orthogonal.

Coherence



- Donoho and Huo introduced the *coherence parameter* μ of a dictionary:

$$\mu = \max_{j \neq k} |\langle \varphi_{\omega_j}, \varphi_{\omega_k} \rangle|$$

- Measures how much distinct atoms look alike

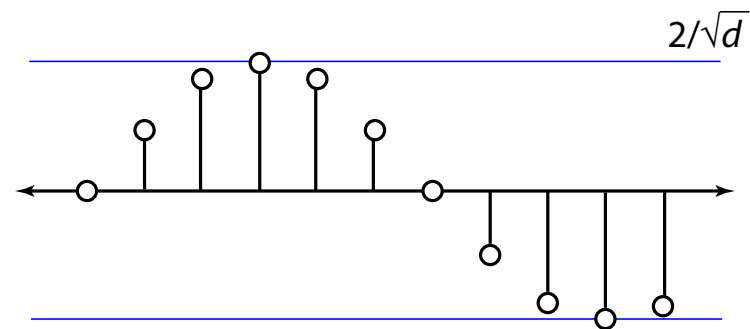
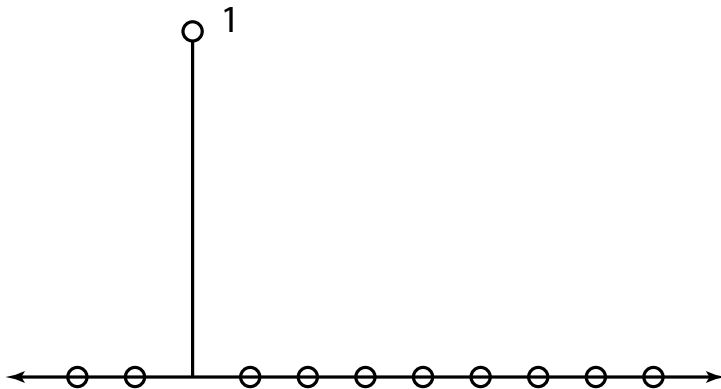
Coherence



- Donoho and Huo introduced the *coherence parameter* μ of a dictionary:

$$\mu = \max_{j \neq k} |\langle \varphi_{\omega_j}, \varphi_{\omega_k} \rangle|$$

- Measures how much distinct atoms look alike
- Many natural dictionaries are incoherent [Donoho–Huo 2000]
- Example: Spikes + sines



Coherence Bounds



☞ In general,

$$\mu \geq \sqrt{\frac{N - d}{d(N - 1)}}$$

☞ If the dictionary contains an orthonormal basis,

$$\mu \geq \sqrt{\frac{1}{d}}$$

Coherence Bounds



☞ In general,

$$\mu \geq \sqrt{\frac{N - d}{d(N - 1)}}$$

☞ If the dictionary contains an orthonormal basis,

$$\mu \geq \sqrt{\frac{1}{d}}$$

☞ Incoherent dictionaries can be *enormous* [GMS 2003]

Quasi-Coherence



- Donoho–Elad [2003] and JAT [2003] independently introduced the *quasi-coherence*:

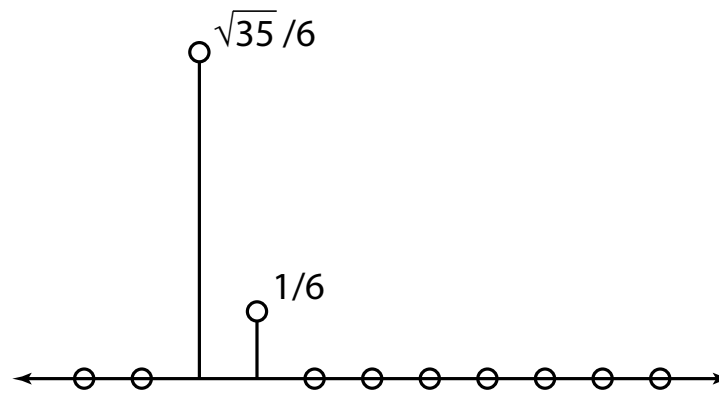
$$\mu_1(m) = \max_{\omega} \max_{\lambda_1, \dots, \lambda_m} \sum_{t=1}^m |\langle \varphi_{\omega}, \varphi_{\lambda_t} \rangle|$$

- Observe that $\mu_1(1) = \mu$
- Generalizes the cumulative coherence: $\mu_1(m) \leq \mu m$

Quasi-Coherence Example



- Consider the dictionary of translates of a double pulse:



- The coherence is $\mu = \sqrt{35}/36$
- The quasi-coherence is

$$\mu_1(m) = \begin{cases} \sqrt{35}/36, & m = 1 \\ \sqrt{35}/18, & m = 2 \\ \sqrt{35}/12, & m \geq 3 \end{cases}$$

Roadmap



- First, a few basic algorithms for sparse approximation
- Then, the role of quasi-coherence in the performance of these algorithms
- Finally, a new algorithm that offers better approximation guarantees

Matching Pursuit (MP)



- In 1993, Mallat and Zhang presented a greedy method for sparse approximation over redundant dictionaries
- Equivalent to Projection Pursuit Regression [Friedman–Stuetzle 1981]
- Developed independently by Qian and Chen [1993]

Matching Pursuit (MP)



- In 1993, Mallat and Zhang presented a greedy method for sparse approximation over redundant dictionaries
 - Equivalent to Projection Pursuit Regression [Friedman–Stuetzle 1981]
 - Developed independently by Qian and Chen [1993]
- Procedure:
 1. Initialize $\mathbf{a}_0 = \mathbf{0}$ and $\mathbf{r}_0 = \mathbf{x}$

Matching Pursuit (MP)



- In 1993, Mallat and Zhang presented a greedy method for sparse approximation over redundant dictionaries
 - Equivalent to Projection Pursuit Regression [Friedman–Stuetzle 1981]
 - Developed independently by Qian and Chen [1993]
- Procedure:
 1. Initialize $\mathbf{a}_0 = \mathbf{0}$ and $\mathbf{r}_0 = \mathbf{x}$
 2. At step t , select an atom φ_{λ_t} that solves

$$\max_{\omega} |\langle \mathbf{r}_{t-1}, \varphi_{\omega} \rangle|$$

Matching Pursuit (MP)



- In 1993, Mallat and Zhang presented a greedy method for sparse approximation over redundant dictionaries
 - Equivalent to Projection Pursuit Regression [Friedman–Stuetzle 1981]
 - Developed independently by Qian and Chen [1993]
- Procedure:
 1. Initialize $\mathbf{a}_0 = \mathbf{0}$ and $\mathbf{r}_0 = \mathbf{x}$
 2. At step t , select an atom φ_{λ_t} that solves

$$\max_{\omega} |\langle \mathbf{r}_{t-1}, \varphi_{\omega} \rangle|$$

3. Form a new approximation and residual

$$\mathbf{a}_t = \mathbf{a}_{t-1} + \langle \mathbf{r}_{t-1}, \varphi_{\lambda_t} \rangle \varphi_{\lambda_t}$$

$$\mathbf{r}_t = \mathbf{r}_{t-1} - \langle \mathbf{r}_{t-1}, \varphi_{\lambda_t} \rangle \varphi_{\lambda_t}$$

Convergence of Matching Pursuit



- Huber [1985] and Jones [1987] developed convergence theory
- Matching Pursuit generates residuals that approach zero:

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq C(\mathcal{D})^m \|\mathbf{x}\|_2$$

- The constant $C(\mathcal{D})$ is essentially the *covering radius* of the dictionary

Convergence of Matching Pursuit



- Huber [1985] and Jones [1987] developed convergence theory
- Matching Pursuit generates residuals that approach zero:

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq C(\mathcal{D})^m \|\mathbf{x}\|_2$$

- The constant $C(\mathcal{D})$ is essentially the *covering radius* of the dictionary
- Prove nothing about whether MP solves the sparse problem
- Until recently, this was the only type of result available

Reference: [Temlyakov 2002]

Sparsity Lost



- DeVore and Temlyakov showed that MP may fail to recover a vector with an exact, sparse representation [1996]

Sparsity Lost



- DeVore and Temlyakov showed that MP may fail to recover a vector with an exact, sparse representation [1996]
- Suppose that \mathcal{D} is an orthonormal basis for \mathbb{C}^d
- Adjoin the unit-norm vector

$$\psi = \alpha \left[\varphi_1 + \varphi_2 + \sum_{n=3}^d \frac{1}{(n-2)^2} \varphi_n \right]$$

Sparsity Lost



- DeVore and Temlyakov showed that MP may fail to recover a vector with an exact, sparse representation [1996]
- Suppose that \mathcal{D} is an orthonormal basis for \mathbb{C}^d
- Adjoin the unit-norm vector

$$\psi = \alpha \left[\varphi_1 + \varphi_2 + \sum_{n=3}^d \frac{1}{(n-2)^2} \varphi_n \right]$$

- Consider the input vector $\mathbf{x} = \varphi_1 + \varphi_2$
- MP continues forever with approximation error

$$\|\mathbf{x} - \mathbf{a}_m\|_2 = O(1/\sqrt{m})$$

Orthogonal Matching Pursuit (OMP)



- Davis, Mallat and Zhang proposed a better greedy method [1997]
- Originally developed by Chen, Billings and Luo [1989]
- Also introduced by Pati, Rezaifar and Krishnaprasad [1993]

Orthogonal Matching Pursuit (OMP)



- Davis, Mallat and Zhang proposed a better greedy method [1997]
 - Originally developed by Chen, Billings and Luo [1989]
 - Also introduced by Pati, Rezaifar and Krishnaprasad [1993]
- Selects atoms the same way as MP
- Computes new approximation and residual via

$$\mathbf{a}_t = \mathbf{a}_{t-1} + \langle \mathbf{r}_{t-1}, \boldsymbol{\varphi}_{\lambda_t}^\perp \rangle \boldsymbol{\varphi}_{\lambda_t}^\perp$$

$$\mathbf{r}_t = \mathbf{r}_{t-1} - \langle \mathbf{r}_{t-1}, \boldsymbol{\varphi}_{\lambda_t}^\perp \rangle \boldsymbol{\varphi}_{\lambda_t}^\perp$$

Orthogonal Matching Pursuit (OMP)



- Davis, Mallat and Zhang proposed a better greedy method [1997]
 - Originally developed by Chen, Billings and Luo [1989]
 - Also introduced by Pati, Rezaifar and Krishnaprasad [1993]
- Selects atoms the same way as MP
- Computes new approximation and residual via

$$\mathbf{a}_t = \mathbf{a}_{t-1} + \langle \mathbf{r}_{t-1}, \boldsymbol{\varphi}_{\lambda_t}^\perp \rangle \boldsymbol{\varphi}_{\lambda_t}^\perp$$

$$\mathbf{r}_t = \mathbf{r}_{t-1} - \langle \mathbf{r}_{t-1}, \boldsymbol{\varphi}_{\lambda_t}^\perp \rangle \boldsymbol{\varphi}_{\lambda_t}^\perp$$

- Convergence similar to MP but stops after d steps [Temlyakov 2002]
- Counterexamples prove OMP may fail to recover sparse superpositions [Chen–Donoho–Saunders 1999]

ℓ_1 Minimization



✿ Chen, Donoho and Saunders introduced a more global approach [1999]

ℓ_1 Minimization



- Chen, Donoho and Saunders introduced a more global approach [1999]
- Replace (\mathcal{D}, m) -SPARSE by a convex relaxation:

$$\min_{\mathbf{b} \in \mathbb{C}^N} \|\mathbf{b}\|_1 \quad \text{subject to} \quad \sum_{\omega \in \Omega} b_{\omega} \varphi_{\omega} = \mathbf{x}$$

- Hope the answers coincide

ℓ_1 Minimization



- Chen, Donoho and Saunders introduced a more global approach [1999]
- Replace (\mathcal{D}, m) -SPARSE by a convex relaxation:

$$\min_{\mathbf{b} \in \mathbb{C}^N} \|\mathbf{b}\|_1 \quad \text{subject to} \quad \sum_{\omega \in \Omega} b_{\omega} \varphi_{\omega} = \mathbf{x}$$

- Hope the answers coincide
- Copious numerical evidence that it succeeds for sparse approximation
- Penalized version for de-noising

ℓ_1 Minimization



- Chen, Donoho and Saunders introduced a more global approach [1999]
- Replace (\mathcal{D}, m) -SPARSE by a convex relaxation:

$$\min_{\mathbf{b} \in \mathbb{C}^N} \|\mathbf{b}\|_1 \quad \text{subject to} \quad \sum_{\omega \in \Omega} b_{\omega} \varphi_{\omega} = \mathbf{x}$$

- Hope the answers coincide
- Copious numerical evidence that it succeeds for sparse approximation
- Penalized version for de-noising
- Computationally burdensome

Recovery Result for ℓ_1 Minimization



Theorem 3. [Donoho–Elad (2003), JAT (2003)] *Assume that \mathcal{D} has quasi-coherence satisfying $\mu_1(m-1) + \mu_1(m) < 1$, and suppose that the vector x has an **exact representation** using m atoms. Then ℓ_1 minimization will recover this exact representation.*

Recovery Result for ℓ_1 Minimization



Theorem 3. [Donoho–Elad (2003), JAT (2003)] *Assume that \mathcal{D} has quasi-coherence satisfying $\mu_1(m-1) + \mu_1(m) < 1$, and suppose that the vector x has an **exact representation** using m atoms. Then ℓ_1 minimization will recover this exact representation.*

Corollary 4. *Assume that \mathcal{D} has coherence μ and that $m < \frac{1}{2}(\mu^{-1} + 1)$. If a vector x has an **exact representation** using m atoms, then ℓ_1 minimization will recover this exact representation.*

Recovery Result for ℓ_1 Minimization



Theorem 3. [Donoho–Elad (2003), JAT (2003)] *Assume that \mathcal{D} has quasi-coherence satisfying $\mu_1(m-1) + \mu_1(m) < 1$, and suppose that the vector x has an **exact representation** using m atoms. Then ℓ_1 minimization will recover this exact representation.*

Corollary 4. *Assume that \mathcal{D} has coherence μ and that $m < \frac{1}{2}(\mu^{-1} + 1)$. If a vector x has an **exact representation** using m atoms, then ℓ_1 minimization will recover this exact representation.*

- For the spike-sine dictionary, $m \leq \sqrt{d}/4$
- For the double-pulse dictionary, works for every m

State-of-Art for ℓ_1 Minimization



- Sharper conditions appear in [Fuchs 2003], [JAT 2003], [Gribonval-Nielsen 2003a, 2003b]
- These papers also study recovery of *exact representations*
- No general method is available for checking these general conditions

Natarajan's Result



- Back in 1995, Natarajan had already developed an approximation result for the forward selection algorithm
- The signal processing community is apparently unfamiliar with his work

Natarajan's Result



- Back in 1995, Natarajan had already developed an approximation result for the forward selection algorithm
- The signal processing community is apparently unfamiliar with his work
- His methods can be adapted to study OMP

Natarajan's Result



- Back in 1995, Natarajan had already developed an approximation result for the forward selection algorithm
- The signal processing community is apparently unfamiliar with his work
- His methods can be adapted to study OMP

Theorem 5. [Natarajan (1995), JAT (2003)] *Assume that \mathcal{D} is a non-redundant dictionary, and suppose that it requires m terms to represent the vector \mathbf{x} with tolerance $\varepsilon/2$. Then Orthogonal Matching Pursuit will compute a representation with error less than ε using no more than*

$$\frac{8m \ln(\|\mathbf{x}\|_2 / \varepsilon)}{\sigma_{\min}(\mathcal{D})} \quad \text{terms.}$$

- *Caveat lector:* Natarajan's paper contains errors

Couvreur and Bresler's Result



- Couvreur and Bresler developed the first proof that an algorithm approximately solves the sparse problem over non-redundant dictionaries

Couvreur and Bresler's Result



- Couvreur and Bresler developed the first proof that an algorithm approximately solves the sparse problem over non-redundant dictionaries

Theorem 6. [Couvreur–Bresler (2000)] *Assume that \mathcal{D} is a non-redundant dictionary. Suppose that the vector \mathbf{y} has an exact representation using m terms. Then there is a number $\delta > 0$ so that $\|\mathbf{x} - \mathbf{y}\|_2 < \delta$ guarantees the backward elimination algorithm will recover the optimal m -term representation of \mathbf{x}*

Couvreur and Bresler's Result



- Couvreur and Bresler developed the first proof that an algorithm approximately solves the sparse problem over non-redundant dictionaries

Theorem 6. [Couvreur–Bresler (2000)] *Assume that \mathcal{D} is a non-redundant dictionary. Suppose that the vector \mathbf{y} has an exact representation using m terms. Then there is a number $\delta > 0$ so that $\|\mathbf{x} - \mathbf{y}\|_2 < \delta$ guarantees the backward elimination algorithm will recover the optimal m -term representation of \mathbf{x}*

- The algorithm recovers every vector with an exact representation

Couvreur and Bresler's Result



- Couvreur and Bresler developed the first proof that an algorithm approximately solves the sparse problem over non-redundant dictionaries

Theorem 6. [Couvreur–Bresler (2000)] *Assume that \mathcal{D} is a non-redundant dictionary. Suppose that the vector \mathbf{y} has an exact representation using m terms. Then there is a number $\delta > 0$ so that $\|\mathbf{x} - \mathbf{y}\|_2 < \delta$ guarantees the backward elimination algorithm will recover the optimal m -term representation of \mathbf{x}*

- The algorithm recovers every vector with an exact representation
- They provide no method for computing δ

Redundant Dictionaries, At Last



- In 2003, Gilbert, Muthukrishnan and Strauss published an efficient approximation algorithm for redundant dictionaries

Redundant Dictionaries, At Last



• In 2003, Gilbert, Muthukrishnan and Strauss published an efficient approximation algorithm for redundant dictionaries

Theorem 7. [GMS (2003)] *Assume that \mathcal{D} has coherence μ , and let $m < \frac{1}{8\sqrt{2}} \mu^{-1} - 1$. For every vector \mathbf{x} , Orthogonal Matching Pursuit computes an m -term approximant \mathbf{a}_m with error*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq 8\sqrt{m} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

Redundant Dictionaries, At Last



• In 2003, Gilbert, Muthukrishnan and Strauss published an efficient approximation algorithm for redundant dictionaries

Theorem 7. [GMS (2003)] *Assume that \mathcal{D} has coherence μ , and let $m < \frac{1}{8\sqrt{2}} \mu^{-1} - 1$. For every vector \mathbf{x} , Orthogonal Matching Pursuit computes an m -term approximant \mathbf{a}_m with error*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq 8\sqrt{m} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

Theorem 8. [GMS (2003)] *Assume that \mathcal{D} has coherence μ , and let $m < \frac{1}{32} \mu^{-1}$. For every vector \mathbf{x} , the GMS algorithm computes an m -term approximant \mathbf{a}_m with error*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq \sqrt{1 + 2064 \mu m^2} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

Better Approximation with OMP



- JAT provided a new analysis of Orthogonal Matching Pursuit for quasi-incoherent dictionaries [2003]

Better Approximation with OMP



- JAT provided a new analysis of Orthogonal Matching Pursuit for quasi-incoherent dictionaries [2003]

Theorem 9. *Suppose that \mathcal{D} has quasi-coherence $\mu_1(m) < \frac{1}{2}$. For an arbitrary signal \mathbf{x} , Orthogonal Matching Pursuit computes an m -term approximant \mathbf{a}_m that satisfies*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq \sqrt{1 + C(\mathcal{D}, m)} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2,$$

where we may estimate the constant as

$$C(\mathcal{D}, m) \leq \frac{m(1 - \mu_1(m))}{(1 - 2\mu_1(m))^2}.$$

Corollaries



Corollary 10. *Suppose that $m < \frac{1}{2} \mu^{-1}$ or (more generally) that $\mu_1(m) < \frac{1}{2}$. Then OMP recovers any signal that has an exact m -term representation.*

Corollaries



Corollary 10. *Suppose that $m < \frac{1}{2} \mu^{-1}$ or (more generally) that $\mu_1(m) < \frac{1}{2}$. Then OMP recovers any signal that has an exact m -term representation.*

Corollary 11. *Suppose that $\mu_1(m) < \frac{1}{3}$. For every signal \mathbf{x} , OMP computes an m -term approximant \mathbf{a}_m that satisfies*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq \sqrt{1 + 6m} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

- For the spike-sine dictionary, this corollary applies whenever $m < \sqrt{d}/6$.
- For the double-pulse dictionary, this corollary applies for every m !

A New Algorithm



- The conference paper [TGMS 2003] presents a new greedy algorithm that achieves even better approximation bounds

A New Algorithm



- The conference paper [TGMS 2003] presents a new greedy algorithm that achieves even better approximation bounds

Theorem 12. *Suppose that $\mu_1(m) < \frac{1}{2}$. There is an algorithm that, for any vector \mathbf{x} , produces an m -term approximation \mathbf{a}_m satisfying*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq \sqrt{1 + C(\mathcal{D}, m)} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2,$$

We may bound the constant above using

$$C(\mathcal{D}, m) \leq \frac{2m \mu_1(m)}{(1 - 2\mu_1(m))^2}.$$

Corollaries



Corollary. *If $\mu_1(m) \leq \min\{\frac{1}{4}, m^{-1}\}$, the error bound simplifies to*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq 3 \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

Corollaries



Corollary. *If $\mu_1(m) \leq \min\{\frac{1}{4}, m^{-1}\}$, the error bound simplifies to*

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq 3 \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

✪ For the double-pulse dictionary, the theorem only provides error bound

$$\|\mathbf{x} - \mathbf{a}_m\|_2 \leq \sqrt{1 + 6m} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2$$

✪ Need $\mu_1(m) = O(m^{-1})$ to obtain significant savings

Overview of New Algorithm



A two-phase greedy pursuit:

- Use OMP to produce a partial approximation with moderate error
- Use Energy Pursuit to refine the first approximation

Energy Pursuit



- Fix a level of sparsity m
- Let \mathbf{x} be a vector
- Select m atoms that carry the most energy:

$$\text{maximize } \sum_{t=1}^m |\langle \mathbf{x}, \varphi_{\lambda_t} \rangle|$$

Energy Pursuit



- Fix a level of sparsity m
- Let \mathbf{x} be a vector
- Select m atoms that carry the most energy:

$$\text{maximize } \sum_{t=1}^m |\langle \mathbf{x}, \varphi_{\lambda_t} \rangle|$$

- For orthonormal bases, equivalent to truncation of Fourier expansion

Reference: [GMS 2003]

Combining the Phases



Suppose that an oracle provides the smallest number T so that T steps of Orthogonal Matching Pursuit yield an approximation \mathbf{a}_T satisfying

$$\|\mathbf{x} - \mathbf{a}_T\|_2 \leq \sqrt{1 + \frac{m(1 - \mu_1(m))}{(1 - 2\mu_1(m))^2}} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

Combining the Phases



Suppose that an oracle provides the smallest number T so that T steps of Orthogonal Matching Pursuit yield an approximation \mathbf{a}_T satisfying

$$\|\mathbf{x} - \mathbf{a}_T\|_2 \leq \sqrt{1 + \frac{m(1 - \mu_1(m))}{(1 - 2\mu_1(m))^2}} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

The Algorithm

- Perform T steps of Orthogonal Matching Pursuit to get T atoms

Combining the Phases



Suppose that an oracle provides the smallest number T so that T steps of Orthogonal Matching Pursuit yield an approximation \mathbf{a}_T satisfying

$$\|\mathbf{x} - \mathbf{a}_T\|_2 \leq \sqrt{1 + \frac{m(1 - \mu_1(m))}{(1 - 2\mu_1(m))^2}} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

The Algorithm

- Perform T steps of Orthogonal Matching Pursuit to get T atoms
- Perform Energy Pursuit on the residual to get $(m - T)$ more atoms

Combining the Phases



Suppose that an oracle provides the smallest number T so that T steps of Orthogonal Matching Pursuit yield an approximation \mathbf{a}_T satisfying

$$\|\mathbf{x} - \mathbf{a}_T\|_2 \leq \sqrt{1 + \frac{m(1 - \mu_1(m))}{(1 - 2\mu_1(m))^2}} \|\mathbf{x} - \mathbf{a}_{\text{opt}}\|_2.$$

The Algorithm

- Perform T steps of Orthogonal Matching Pursuit to get T atoms
- Perform Energy Pursuit on the residual to get $(m - T)$ more atoms
- Compute the m -term approximation by projecting \mathbf{x} onto the subspace spanned by the chosen atoms

Avoiding a Trip to Delphi



Method I

Guess the value of T by running the algorithm $(m + 1)$ times with $T = 0, 1, \dots, m$.

Avoiding a Trip to Delphi



Method I

Guess the value of T by running the algorithm $(m + 1)$ times with $T = 0, 1, \dots, m$.

Method II

Guess the optimal error by running the algorithm with errors taken from a geometric progression ranging between the machine precision and the norm of the input function.

Avoiding a Trip to Delphi



Method I

Guess the value of T by running the algorithm $(m + 1)$ times with $T = 0, 1, \dots, m$.

Method II

Guess the optimal error by running the algorithm with errors taken from a geometric progression ranging between the machine precision and the norm of the input function.

- Both methods are embarrassingly parallel, although efficient serial versions are also possible
- We can select the best of the multiple solutions

Approximate Nearest Neighbors



- Both phases of the algorithm require finding an atom from the dictionary that has maximal inner product with an input vector
- In a naïve implementation, this is the most time-consuming step

Approximate Nearest Neighbors



- Both phases of the algorithm require finding an atom from the dictionary that has maximal inner product with an input vector
- In a naïve implementation, this is the most time-consuming step
- We can quickly find inner products that are *nearly maximal* using an *Approximate Nearest Neighbors* data structure

Approximate Nearest Neighbors



- Both phases of the algorithm require finding an atom from the dictionary that has maximal inner product with an input vector
- In a naïve implementation, this is the most time-consuming step
- We can quickly find inner products that are *nearly maximal* using an *Approximate Nearest Neighbors* data structure
- The cost of a query is comparable to the cost of looking at each entry of the vector
- It takes significant preprocessing to build the data structure

Approximate Nearest Neighbors



- Both phases of the algorithm require finding an atom from the dictionary that has maximal inner product with an input vector
- In a naïve implementation, this is the most time-consuming step
- We can quickly find inner products that are *nearly maximal* using an *Approximate Nearest Neighbors* data structure
- The cost of a query is comparable to the cost of looking at each entry of the vector
- It takes significant preprocessing to build the data structure
- It can be shown that this implementation of the algorithm succeeds with slightly weaker error bounds

References: [Charikar 2003]

New Horizons



- Understand structured coherent dictionaries
- Develop approximation results for ℓ_1 minimization
- Study more sophisticated greedy algorithms
- Compute *a posteriori* error bounds
- Address subset selection problems
- Examine other sparsity measures
- Consider sparse approximation in Banach spaces
- Pursue simultaneous sparse approximation
- . . .

Papers & Contact Information



- ❧ JAT. “Greed is Good: Algorithmic Results for Sparse Approximation.” ICES Report 0304, The University of Texas at Austin, Feb. 2003.
- ❧ JAT. “Recovery of Short, Complex Linear Combinations via ℓ_1 Minimization.” Unpublished note, Aug. 2003.
- ❧ TGMS. “Improved Sparse Approximation over Quasi-Incoherent Dictionaries.” *Proc. of the 2003 Intl. Conf. on Image Processing*, Barcelona, Sept. 2003.
- ❧ Other material will appear in JAT’s dissertation
- ❧ For more information, contact [<jtropp@ices.utexas.edu>](mailto:jtropp@ices.utexas.edu)