

Provable Learning of Feature Representations

Anima Anandkumar

U.C. Irvine

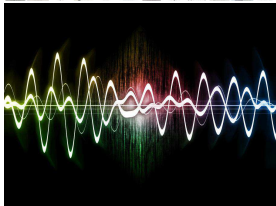
Feature learning as cornerstone of ML

ML Practice



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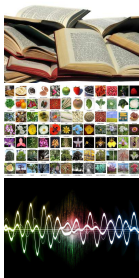
ML Papers

Label	Features				
0	2.1	5.2	0	0	—
1	0	0	2	1	—
1	1.1	0	0	0	—
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Feature learning as cornerstone of ML

- Find efficient representation of data, e.g. based on **sparsity**, low dimensional structures etc.

ML Practice



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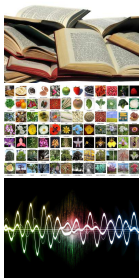
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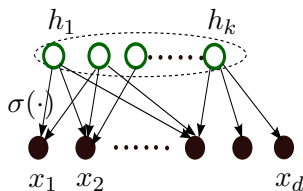
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- Feature engineering typically critical for good performance
- Deep learning has shown considerable promise for feature learning
- Can we provide principled approaches which are guaranteed to learn good features?**

Neural Networks and Unsupervised Learning

Belief Networks/Boltzmann Machines

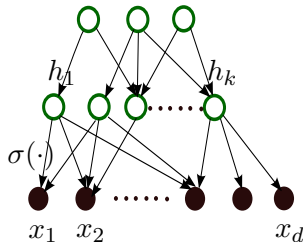
- Observation: $x = \sigma(Ah + b)$, where $\sigma(\cdot)$ is any (non-linear) function.
- $x \in \mathbb{R}^d$ and $h \in \mathbb{R}^k$.
- Unsupervised setting: h is unobserved.
- Deep networks: $\sigma(\cdot)$ applied recursively.
- Probabilistic model: $\mathbb{E}[x|h] = \sigma(Ah + b)$.



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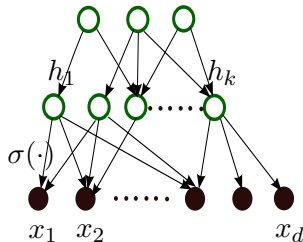
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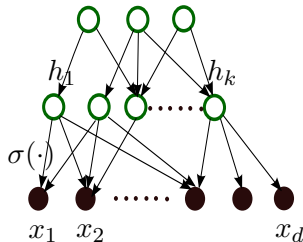


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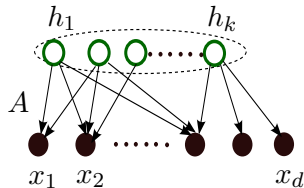
Learning

- Through **gradient descent**.
- **Non-convex**: no guarantees in general.

In this talk: methods and guarantees for learning neural networks

Linear Neural Networks

- Observed sample $x = Ah$.
- h is hidden variable and A is dictionary.
- $x \in \mathbb{R}^d$, $h \in \mathbb{R}^k$ and $A \in \mathbb{R}^{d \times k}$.

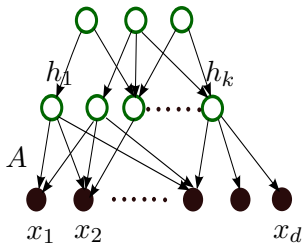


Observations

- Deep networks can be collapsed: **1-layer** networks suffice.
- Poor performance in practice.
- Natural to first analyze linear models.

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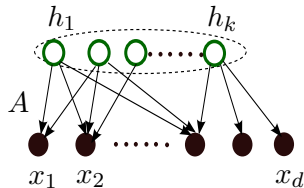


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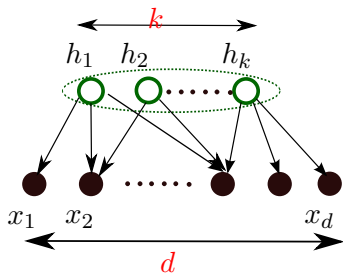
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Learning Linear Networks through SVD

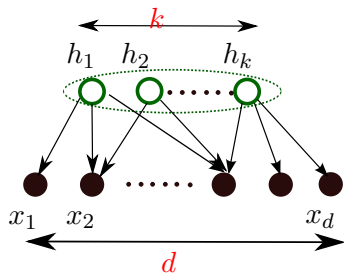


- Linear model: $x = Ah$.
- Pairwise moments: $M_2 = \mathbb{E}[xx^\top] = A\mathbb{E}[hh^\top]A^\top$.
- SVD: $M_2 = U\Lambda U^\top$: a valid linear representation.
- Learning through SVD: cannot learn overcomplete representations.
($k > d$) learnable?
- SVD cannot enforce **sparsity**, **non-negativity** etc.

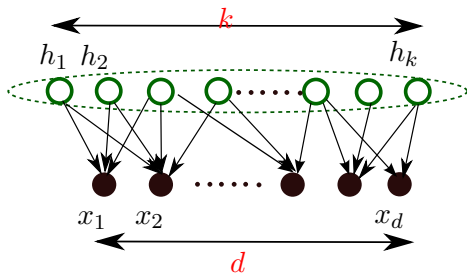
Learning Overcomplete Representations

- Latent dimensionality k and observed dimensionality d .

Undercomplete Representation



Overcomplete Representation



Works Analyzing Learning Linear Networks

In deep learning community

- No local optima for SVD: Baldi and Hornik '89.
- Dynamics of learning linear networks: Saxe et al '13.
- Undercomplete case and learning SVD representations.

In learning theory community (undercomplete models)

- Sparse representations: Spielman et. al'12, Anandkumar et. al'13.
- Non-negativity (topic modeling): Arora et. al. '12.
- Dirichlet models (LDA topic models): Anandkumar et. al. '12.

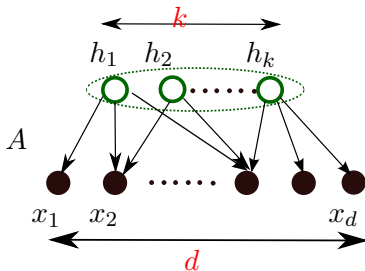
In learning theory community (overcomplete models)

- Concurrent works of Arora et. al. and Anandkumar et. al. for sparse coding
- Non-linear sparse representations: Arora et. al. '14.
- Overcomplete latent variable models: Anandkumar et. al. '14.

Outline

- 1 Introduction
- 2 Learning Linear Sparse Representations**
- 3 Learning Overcomplete Sparse Representations
- 4 Experiments
- 5 Other Works and Conclusion

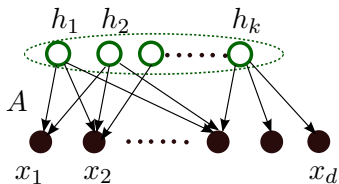
Learning Linear Sparse Representations



- Linear Model: $x = Ah$.
- Sparse representation: A is sparse.
- SVD need not give rise to sparse representations.

Guaranteed methods for learning sparse representations

Intuitions..

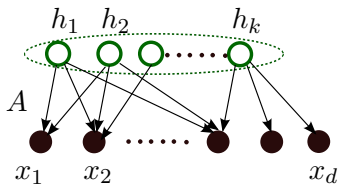


Learning using second-order moments

- Linear model: $x = Ah.$ and $\mathbb{E}[xx^\top] = A\mathbb{E}[hh^\top]A^\top$
- Learning: recover A from $A\mathbb{E}[hh^\top]A^\top$.

Ill-posed without further restrictions

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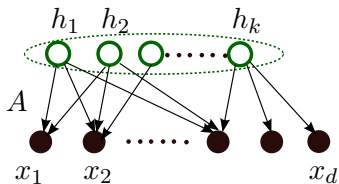
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Ill-posed without further restrictions

- When h is not degenerate: recover A from $\text{Col}(A)$
- Can we recover a **sparse** A ?

Intuitions..



Learning using second-order moments

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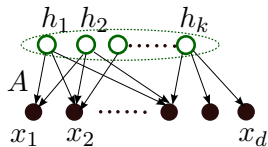
Sparsity constraints on topic-word matrix A

- Main constraint: columns of A are **sparsest** vectors in $\text{Col}(A)$

Sufficient Conditions for Identifiability

columns of A are **sparsest** vectors in $\text{Col}(A)$

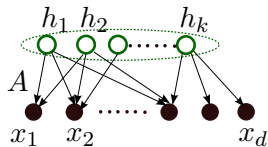
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Sufficient Conditions for Identifiability

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- Sufficient conditions?



Structural Condition: (Additive) Graph Expansion

$$|\mathcal{N}(S)| \geq |S| + d_{\max}, \text{ for all } S \subset [k]$$

Parametric Conditions: Generic Parameters

$$\|Av\|_0 > |\mathcal{N}_A(\text{supp}(v))| - |\text{supp}(v)|$$

Tractable Algorithm for Unmixing

Unmixing Task

Recover topic-word matrix A from $A\mathbb{E}[hh^\top]A^\top$.

Exhaustive search

$$\min_{z \neq 0} \|Az\|_0$$

Convex relaxation

$$\min_z \|Az\|_1, \quad b^\top z = 1,$$

where b is a row in A .

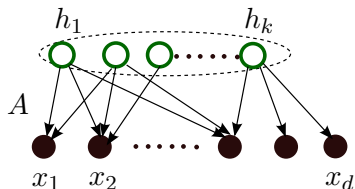
Change of Variables

$$\min_w \|(A\mathbb{E}[hh^\top]A^\top)^{1/2}w\|_1, \quad e_i^\top (A\mathbb{E}[hh^\top]A^\top)^{1/2}w = 1.$$

Under “reasonable” conditions, the above program exactly recovers A

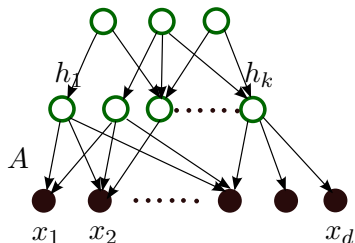
“Learning Latent Bayesian Networks and Topic Models Under Expansion Constraints” by A. Anandkumar, D. Hsu, A. Javanmard and S.M. Kakade. ICML, June 2013.

Learning Hierarchical Sparse Representations



- So far: recover topic-word matrix A from $A\mathbb{E}[hh^\top]A^\top$.
- Repeat the process to obtain hierarchical models.

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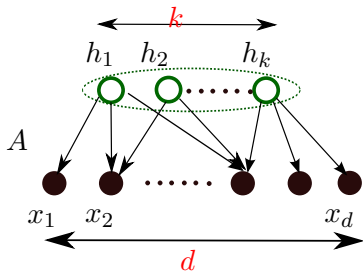
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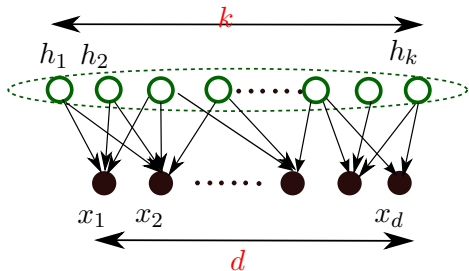
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Undercomplete Representation



Overcomplete Representation



When are overcomplete models ($k > d$) learnable?

Dictionary Learning or Sparse Coding

- Each sample is a **sparse** combination of dictionary atoms.

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Setup

- No. of dictionary elements $k >$ observed dimensionality d .
- Linear model: $X = AH$.
- $A = [a_1, \dots, a_k]$: dictionary elements
- $x \in \mathbb{R}^d$: Observation. $X = [x_1, \dots, x_n] \in \mathbb{R}^{d \times n}$: Observation matrix.

Main Assumptions

- H is **sparse**: each column is randomly s -sparse
Each sample is a combination of s dictionary atoms.

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Main Assumptions

- H is **sparse**: each column is randomly s -sparse
Each sample is a combination of s dictionary atoms.
- A is **incoherent**: $\max_{i \neq j} |\langle a_i, a_j \rangle| \approx 0$.

Intuitions: how incoherence helps

- Each sample is a combination of dictionary atoms: $x_i = \sum_j h_{i,j} a_j$.
- Consider x_i and x_j s.t. they have **no common dictionary atoms**.
- What about $|\langle x_i, x_j \rangle|$?

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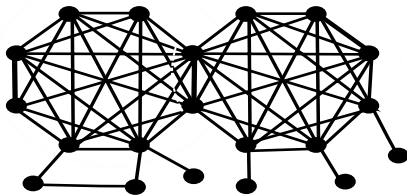
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Construction of Correlation Graph

- Nodes: Samples x_1, \dots, x_n .
- Edges: $|\langle x_i, x_j \rangle| > \tau$ for some threshold τ .

How does the correlation graph help in dictionary learning?

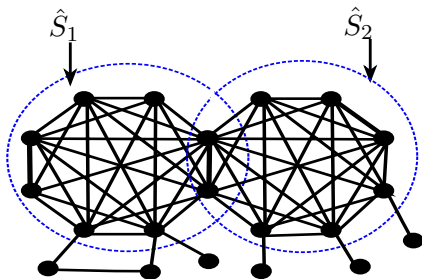
Correlation Graph and Clique Finding



Main Insight

- (x_i, x_j) : edge in correlation graph $\Rightarrow x_i$ and x_j have **at least one dictionary element in common.**

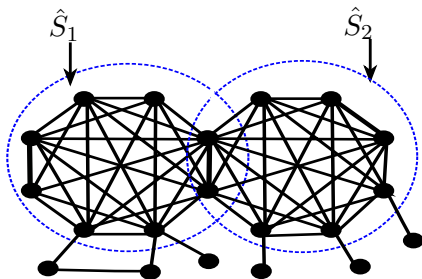
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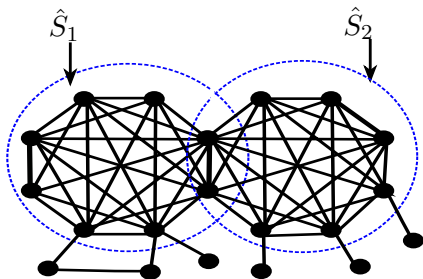
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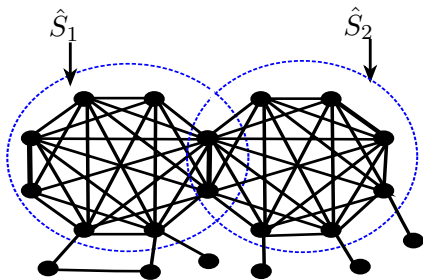
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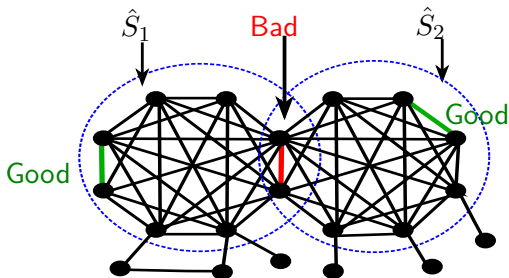
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Result on Approximate Dictionary Estimation

Procedure

- Start with a random edge (x_{i^*}, x_{j^*}) .
- \hat{S} = common nbd. of x_{i^*} and x_{j^*} . If \hat{S} is close to a **clique**, accept.
- Estimate a dictionary element via **top singular vector** of $\sum_{i \in \hat{S}} x_i x_i^T$.

Theorem

The dictionary A can be estimated with **bounded error** w.h.p. when $s = o(k^{1/3})$ and number of samples $n = \omega(k)$.

- Exact estimation when H is **discrete**, e.g. Bernoulli.

A. Agarwal, A., P. Netrapalli. "Exact Recovery of Sparsely Used Overcomplete Dictionaries,"
Preprint, Sept. 2013.

Exact Estimation via Alternating Minimization

- So far.. **approximate** dictionary estimation. What about **exact** estimation for arbitrary H ?

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Alternating Minimization

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- Re-estimate A via **Least Squares**.

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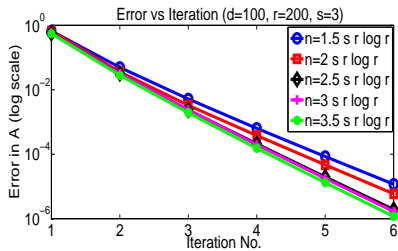
The above method converges to the **true solution** (A, H) at a **linear rate** w.h.p. when $s < \min(k^{1/8}, d^{1/9})$ and number of samples $n = \Omega(k^2)$.

Outline

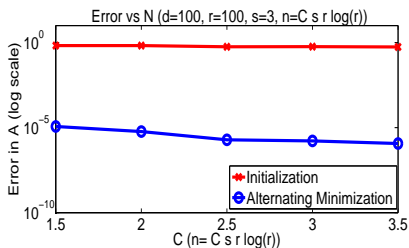
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Simulations

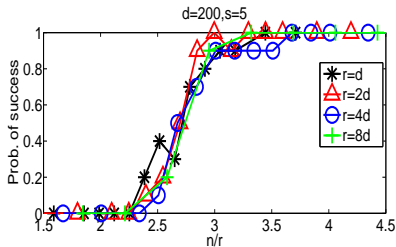
Local linear convergence



One-shot vs alternating



Sample complexity



Experiments on MNIST

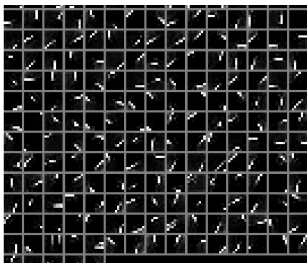
Original



Reconstruction



Learnt Representation

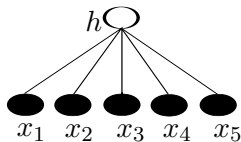


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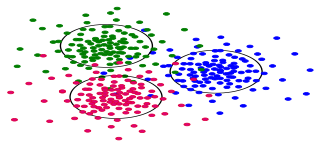
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Tensor Methods for Unsupervised Learning

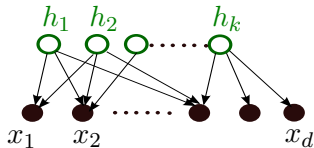
Multi-view mixtures



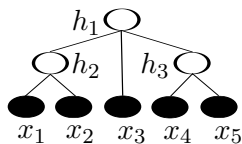
Spherical Gaussian mixtures



Indep. Component Analysis



HMM/Latent Trees



- Talk at spectral learning workshop at 15:40 today.

Conclusion

Learning Feature Representations

- Guaranteed unsupervised learning is possible in many cases
- Exploit availability of large number of **unlabelled** samples
- Overcomplete models provide **flexibility** in modeling, robust to **noise**

Learning Linear Networks (Undercomplete)

- Learning under expansion. Guaranteed learning through ℓ_1 .

Learning Linear Networks (Overcomplete)

- Each sample is a **sparse** combination of dictionary atoms.
- Guarantees through **clique finding** and **alternating minimization**.

Outlook

- Extend guarantees to non-linear setting.
- Representational power of such networks.